



SNS COLLEGE OF ENGINEERING

Kurumbapalayam (Po), Coimbatore – 641 107

An Autonomous Institution

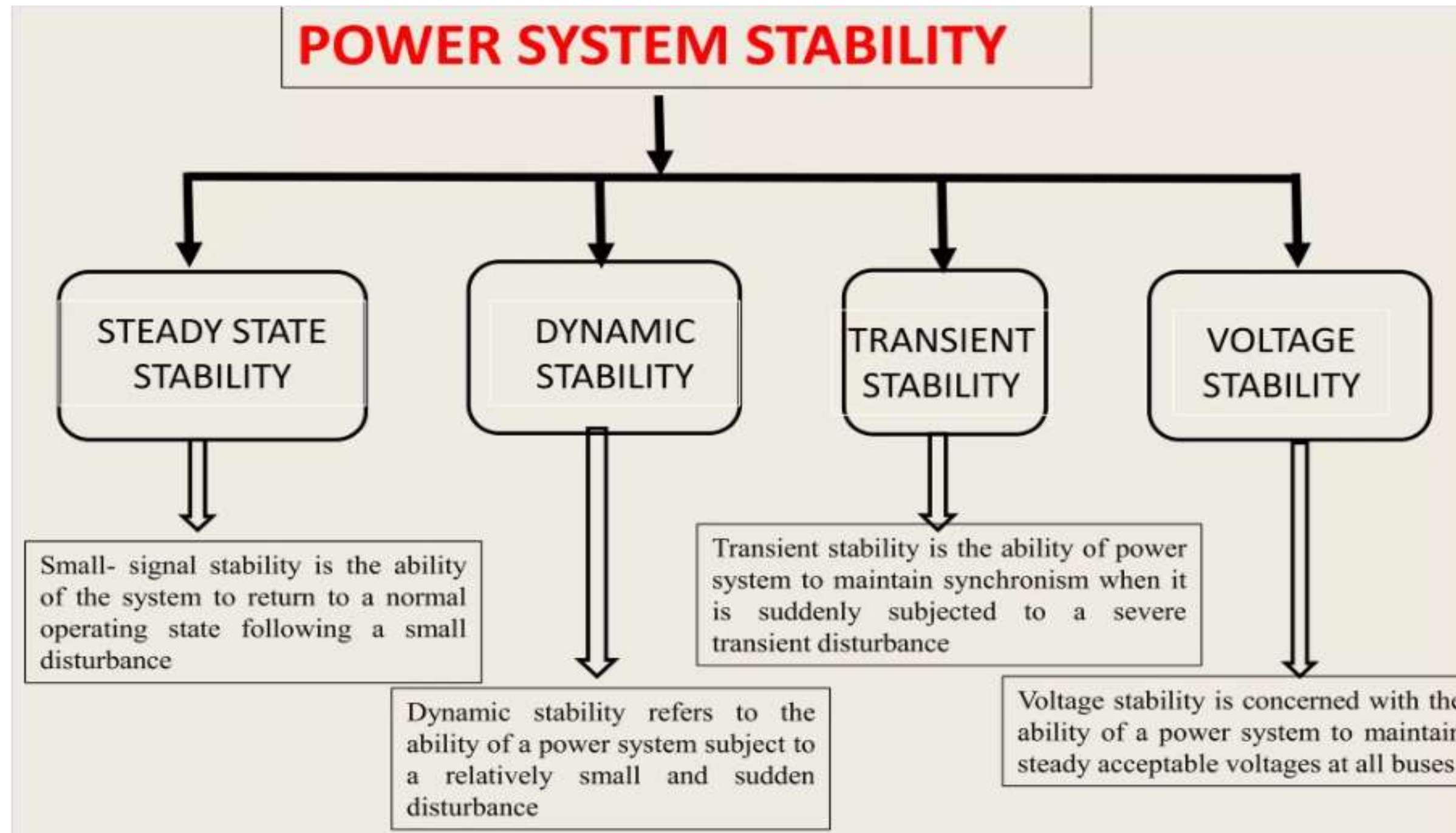
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DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING

UNIT – V

Stability Studies and Reactive Power Compensation
Power System Stability







TRANSIENT STABILITY

- It is the ability of the power grid system to maintain synchronism when subjected to severe disturbances.
- Transient stability analysis is considered with large disturbances like :
 - Suddenly change in load
 - Generation or transmission system configuration due to fault
 - Switching

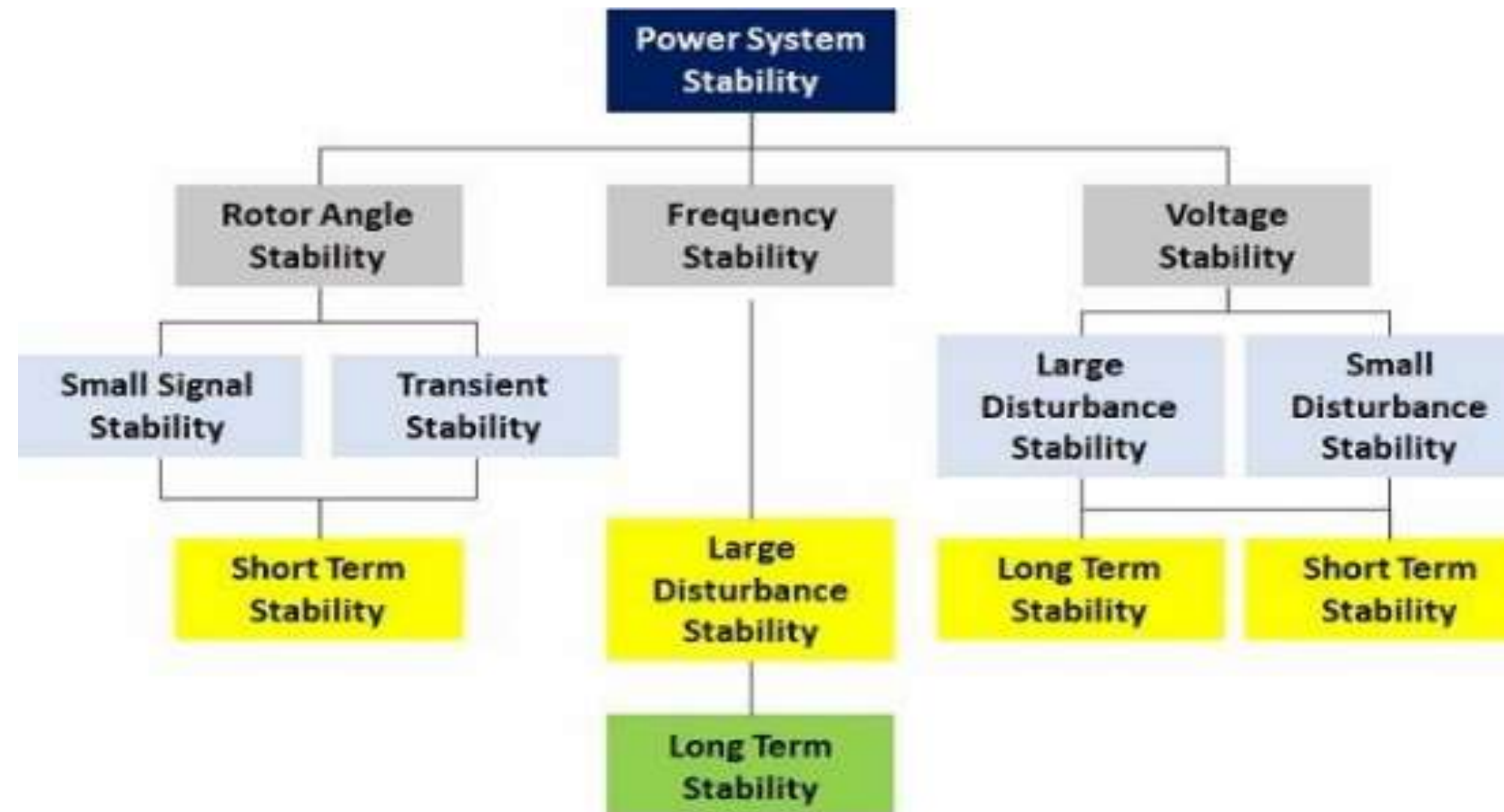


ROTOR ANGLE STABILITY

- It is the ability of the system to remain in synchronism when subjected to a disturbance.
- The rotor angle of a generator depends on the balance between the electromagnetic torque due to the input mechanical power through prime mover.
- Remaining in synchronism means that all the generators electromagnetic torque is exactly balanced by the mechanical torque .
- In some generators the balance between electromagnetic and mechanical torque is disturbed which leads to disturbance in oscillations and rotor angle.



Classification of power system stability





VOLTAGE STABILITY

- Voltage stability refer to the ability of power system to maintain steady voltages at all buses in a system after being subjected to a disturbance from a given initial operating point.
- The system state enters the voltage instability region when a disturbance or an increase in load demand or alteration in system state results in an uncontrollable and continuous drop in system voltage.



DYNAMICS OF SYNCHRONOUS MACHINE

The kinetic energy of the rotor at synchronous machine is,

$$K.E = \frac{1}{2} J \omega_{sm}^2 \times 10^{-6} \text{ MJ}$$

Where,

J = rotor moment of inertia in $Kg.m^2$

ω_{sm} = rotor speed in radian (mechanical)/second

But $\omega_s = \left(\frac{P}{2}\right) \omega_{sm}$ rotor speed in radian (electrical)/second

Where P is no of machine poles.

$$K.E = \frac{1}{2} \left[J \left(\frac{2}{P}\right)^2 \omega_s \times 10^{-6} \right] \times \omega_s$$

$$K.E = \frac{1}{2} M \omega_s$$

Where, $M = J \left(\frac{2}{P}\right)^2 \omega_s \times 10^{-6}$ moment of inertia in $MJ.S/(elect \text{ rad})$

$GH = K.E = \frac{1}{2} M \omega_s$, Where G is machine rating in MVA and H is inertia constant in MJ/MVA



DYNAMICS OF SYNCHRONOUS MACHINE

$$M = \frac{2GH}{\omega_s} = \frac{GH}{\pi f} \quad \text{MJ.S/(elect rad)}$$

$$M = \frac{GH}{180f} \quad \text{MJ.S/(elect degree)}$$



ASSESSMENT

1. What is the value of transient stability limit?
 - Higher than steady state limit
 - **Lower than steady state limit**
 - Depending upon the severity to load
 - All of these



ASSESSMENT

2. By using which component can the transient stability limit of a power system be improved?

- Series resistance
- **Series capacitor**
- Series inductor
- Shunt resistance

