

Functional units – Basic operational concepts – Bus Structures – Performance – Memory locations and addresses – Memory operations – Instruction and Instruction sequencing – **Addressing modes – Assembly language** – Case study: RISC and CISC Architecture.











Addressing modes

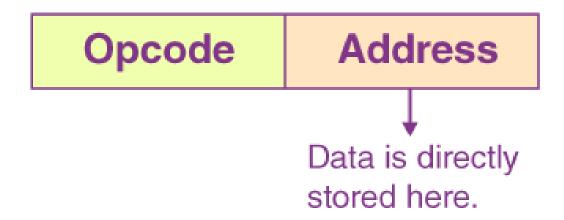
- The different ways of specifying the location of an operand in an instruction are called as **addressing modes**.
- **Starting address** of memory segment.
- **Effective address or Offset**: An offset is determined by adding any combination of three address elements: **displacement, base and index.**
 - **Displacement:** It is an 8 bit or 16 bit immediate value given in the instruction.
 - **Base**: Contents of base register, BX or BP.
 - **Index**: Content of index register SI or DI.



- mplied / Implicit Addressing Mode Stack Addressing Mode Immediate Addressing Mode Direct Addressing Mode Indirect Addressing Mode Register Direct Addressing Mode Types Of Addressing Mode : Register Indirect Addressing Mode → Relative Addressing Mode Indexed Addressing Mode Base Register Addressing Mode Auto-Increment Addressing Mode Auto-Decrement Addressing Mode
- 1. Implied / Implicit Addressing Mode
- 2. Stack Addressing Mode
- 3. Immediate Addressing Mode
- 4. Direct Addressing Mode
- 5. Indirect Addressing Mode
- 6. Register Direct Addressing Mode
- 7. Register Indirect Addressing Mode
- 8. Relative Addressing Mode
- 9. Indexed Addressing Mode
- 10. Base Register Addressing Mode
- 11. Auto-Increment Addressing Mode
- 12. Auto-Decrement Addressing Mode



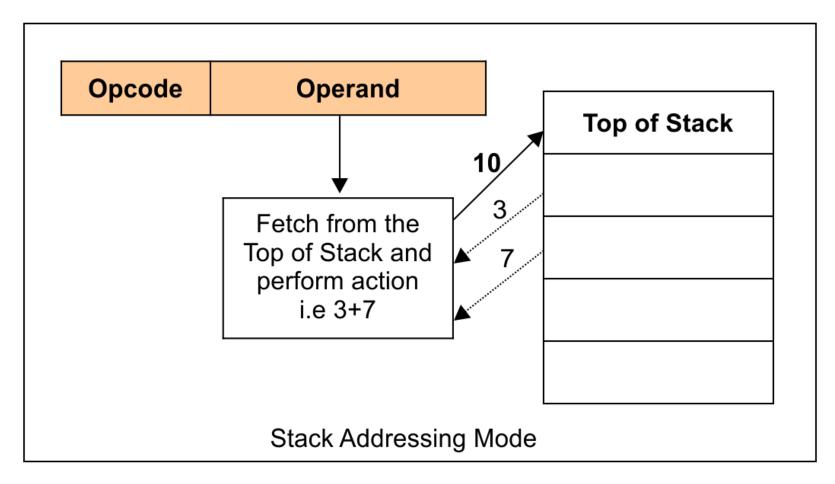
Implied / Implicit Addressing Mode



Example: MOV AL, 35H (move the data 35H into AL register)

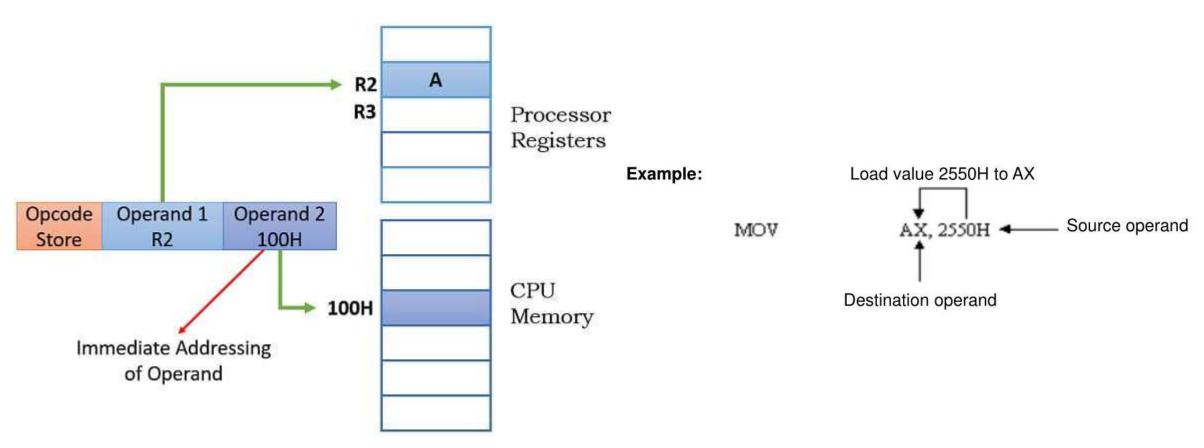


Stack Addressing Mode



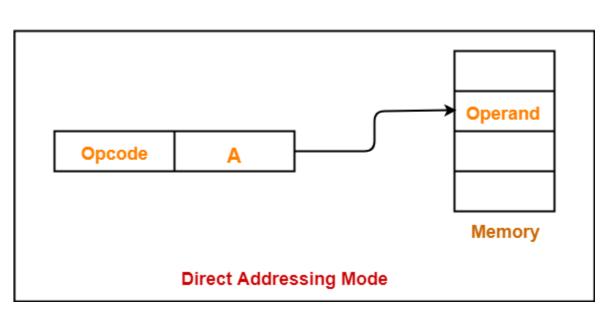


Immediate Addressing Mode





Direct Addressing Mode

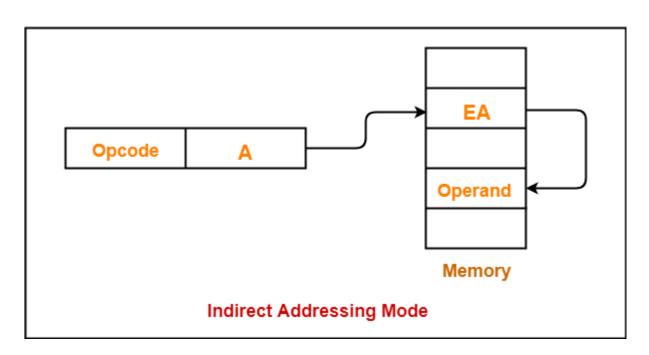


ADD X will increment the value stored in the accumulator by the value stored at memory location X.

$$AC \leftarrow AC + [X]$$



Indirect Addressing Mode

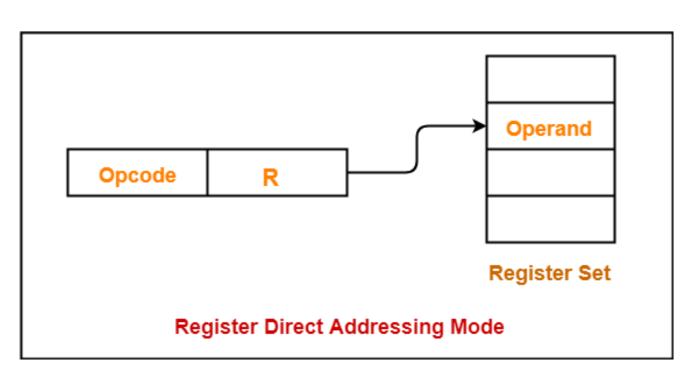


ADD X will increment the value stored in the accumulator by the value stored at memory location specified by X.

$$AC \leftarrow AC + [[X]]$$



Register Direct Addressing Mode

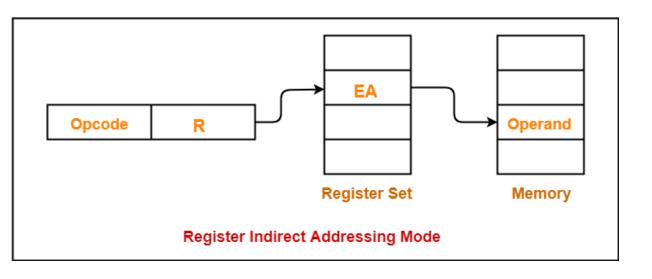


ADD R will increment the value stored in the accumulator by the content of register R.

$$AC \leftarrow AC + [R]$$



Register Indirect Addressing Mode

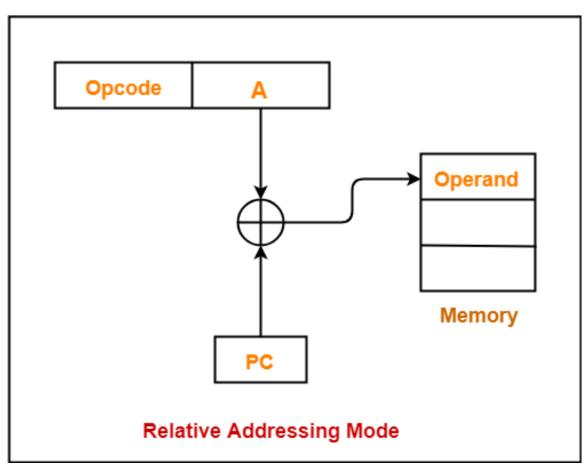


ADD R will increment the value stored in the accumulator by the content of memory location specified in register R.

$$AC \leftarrow AC + [[R]]$$



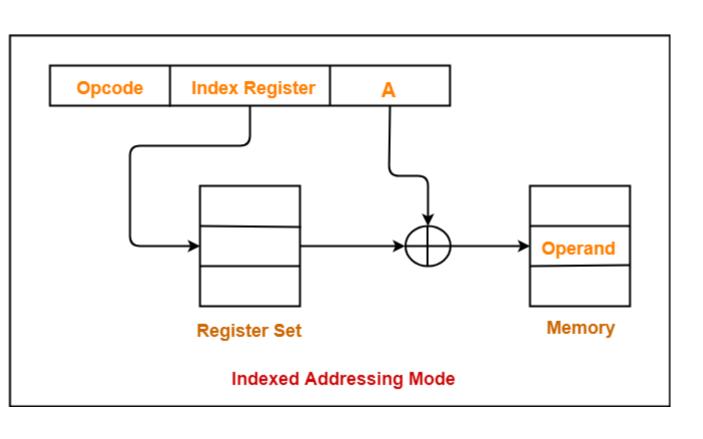
Relative Addressing Mode



Effective Address
= Content of Program Counter +
Address part of the instruction



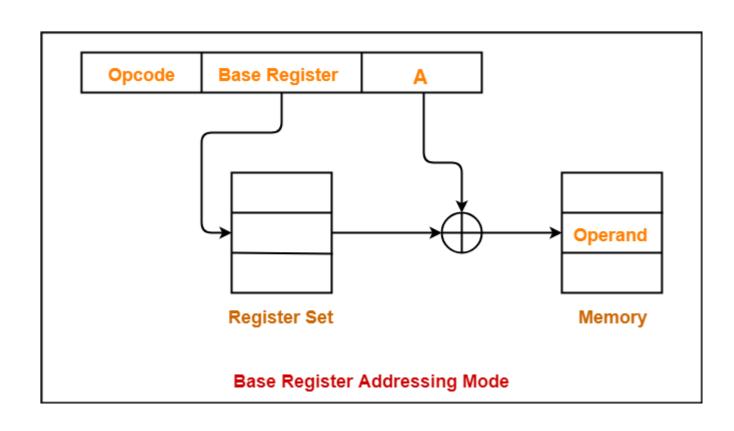
Indexed Addressing Mode



Effective Address
= Content of Index Register +
Address part of the instruction



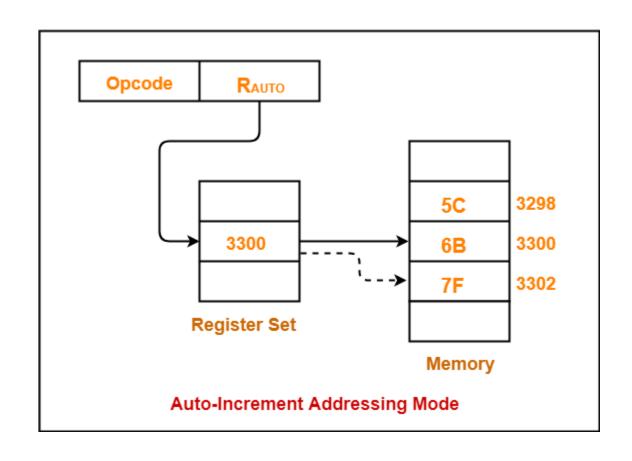
Base Register Addressing Mode



Effective Address
= Content of Base Register +
Address part of the
instruction

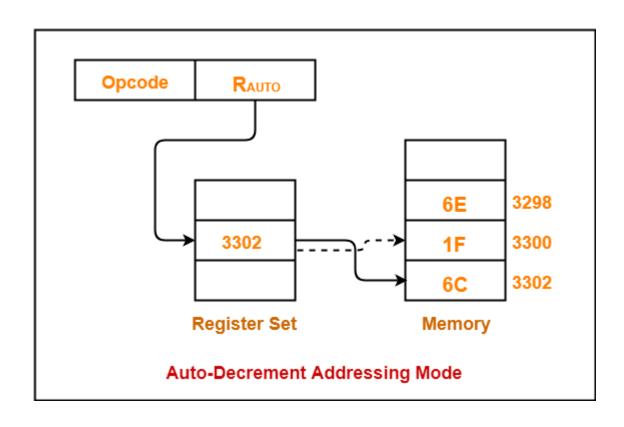


Auto-Increment Addressing Mode





Auto-Decrement Addressing Mode



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Addressing Modes	Applications
Immediate Addressing Mode	To initialize registers to a constant value
Direct Addressing Mode and Register Direct Addressing Mode	To access static data To implement variables
Indirect Addressing Mode and Register Indirect Addressing Mode	To implement pointers because pointers are memory locations that store the address of another variable To pass array as a parameter because array name is the base address and pointer is needed to point the address
Relative Addressing Mode	For program relocation at run time i.e. for position independent code To change the normal sequence of execution of instructions For branch type instructions since it directly updates the program counter
Index Addressing Mode	For array implementation or array addressing For records implementation
Base Register Addressing Mode	For writing relocatable code i.e. for relocation of program in memory even at run time For handling recursive procedures
Auto-increment Addressing Mode & Auto-decrement Addressing Mode	For implementing loops For stepping through arrays in a loop For implementing a stack as push and pop



Assembly language

- Assembly language is a type of programming language that communicates with the hardware of a computer.
- Hardware from different manufacturers uses machine language, like binary or hexadecimal characters, to perform tasks.



Assembly language

• Assignment Statement is f = (g + h) - (i + j). What is the compiled MIPS code?

f,g,h,i,j is assigned to r0,r1,r2,r3,r4 Temp register r5,r6

add r5, r1, r2 add r6, r3, r4 sub r0, r5, r6



Assembly language

Convert the following C Language into MIPS Assembly Language A[30] = h + A[30]

lw \$t0, 32(\$s4) # load word add \$t0, \$s2, \$t0 sw \$t0, 32(\$s4) # store word



Index 8 requires offset of 32

Assignment statement is g = h + A[8];

A[12] = h + A[8];

lw \$t0, 8(\$s3) # load word add \$s1, \$s2, \$t0

lw \$t0, 32(\$s3) # load word add \$t0, \$s2, \$t0 sw \$t0, 48(\$s3) # store word



C code:

```
if (i==j)

f = g+h;

else f = g-h;

- f, g, ... in $s0, $s1, ...
```

Compiled MIPS code:

beq \$s3, \$s4, Else add \$s0, \$s1, \$s2 j Exit Else: sub \$s0, \$s1, \$s2 Exit: ...

