



LTI DT System Analysis using Z Transform

The output
$$y(n)$$
 of discrete time LTI system is $2(y_3)^n u(n)$ when the input signal $x(n) = u(n)$. find the inpulse response of the dystem.

$$y(z) = 2\left(\frac{z}{z-1/3}\right) \qquad x(z) = \frac{z}{z-1}$$

$$H(z) = \frac{\chi(z)}{\chi(z)} = \frac{2\left(\frac{z-1/3}{z}\right)}{\frac{z}{2}}$$

$$H(z) = \frac{2z(z-1)}{z(z-1/3)} \Rightarrow \frac{H(z)}{z} = \frac{2(z-1)}{z(z-1/3)}$$

$$\frac{2(z-1)}{z(z-1/3)} = \frac{A}{z} + \frac{B}{z-1/3}$$

$$2(z-1) = A(z-\frac{1}{3}) + B(z)$$

$$\frac{H(z)}{z} = \frac{b}{z} - \frac{4}{z - \frac{1}{3}}$$

$$H(z) = 6 \left(\frac{z}{z} \right) - 4 \left(\frac{z}{z - \frac{1}{3}} \right)$$





② compute the response of the system y(n) = 0.7y(n-1) - 0.12y(n-2) + x(n-1) + x(n-2) to the ilp <math>x(n) = n u(n) is system stable.

y(m) = 0.7y(n-1) - 0.12y(n-2) + x(n-1) + x(n-2)

Taking z-transform on both sides

$$y(z) = 0.7 z^{-1} y(z) - 0.12 z^{-2} y(z) + x(z) z^{-1} + z^{-2} x(z)$$

$$y(z) \left[1-0.7z^{-1} + 0.12z^{-2} \right] = x(z) \left[z^{-1} + z^{-2} \right]$$

$$H(\bar{z}) = \frac{y(\bar{z})}{x(\bar{z})} = \frac{z^{-1} + z^{-2}}{1 - 0.7z^{-1} + 0.12\bar{z}^{-2}}$$

Multiply & Dirac by 22

$$H(x) = \frac{x+1}{x^2 - 0.7x + 0.12}$$

$$= \frac{71}{7^2 - 0.37 - 0.47 + 0.12}$$

$$H(z) = \frac{z+1}{(z-0.3)(z-0.4)}$$

$$\frac{\mathcal{L}(z)}{\chi(z)} = \frac{z+1}{(z-0.3)(z-0.4)}$$

$$y(z) = \chi(z)$$
. $\frac{z+1}{(z-0.3)(z-0.4)}$





$$y(z) = \frac{z}{(z-1)^2}$$

$$y(z) = \frac{z}{(z-1)^2} \frac{z+1}{(z-0.3)(z-0.4)}$$

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$$y(z) = \frac{z}{(z-1)^2} \frac{z+1}{(z-0.3)(z-0.4)}$$

$$\frac{z+1}{(z-1)^2} \frac{1}{(z-0.3)(z-0.4)} + \frac{1}{(z-0.3)^2} \frac{z+1}{(z-0.3)(z-0.4)}$$

$$\frac{z+1}{(z-1)^2} \frac{1}{(z-0.3)(z-0.4)} + \frac{1}{(z-0.4)^2} + \frac{1}{(z-0.4)} + \frac{1}{(z-0.4)^2}$$

$$\frac{z+1}{(z-0.3)(z-0.4)} + \frac{1}{(z-0.3)(z-0.4)} + \frac{1}{(z-0.4)^2} + \frac{1}{(z-0.4)^2} + \frac{1}{(z-0.4)^2}$$

$$\frac{z+1}{z-0.3} = \frac{1}{(z-0.3)(z-0.4)} + \frac{1}{(z-0.3)(z-0.4)} + \frac{1}{(z-0.4)^2} +$$