



# SNS COLLEGE OF TECHNOLOGY

Coimbatore-35

An Autonomous Institution

Accredited by NBA – AICTE and Accredited by NAAC – UGC with 'A+' Grade

Approved by AICTE, New Delhi & Affiliated to Anna University, Chennai

## *DEPARTMENT OF MECHATRONICS*

# 19MCB303 – SENSORS AND SIGNAL PROCESSING

## UNIT 1 – SCIENCE OF MEASUREMENT

### STATIC AND DYNAMIC CHARACTERISTICS

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# Syllabus



## UNIT-I

## SCIENCE OF MEASUREMENT

9

**Units and Standards- Calibration techniques -Errors in Measurements- Generalized Measurement System-Static and dynamic characteristics of transducers- Generalized Performance of Zero Order and First Order Systems - Response of transducers to different time varying inputs - Classification of transducers-Introduction to second order systems.**





# *Characteristics of Transducer*



The various **static characteristics** are:

- i) Accuracy
- ii) Precision
- iii) Sensitivity
- iv) Linearity
- v) Reproducibility
- vi) Repeatability
- vii) Resolution
- viii) Threshold
- ix) Drift
- x) Stability
- xi) Tolerance
- xii) Range or span

The various **dynamic characteristics** are:

- i) Speed of response
- ii) Measuring lag
- iii) Fidelity
- iv) Dynamic error

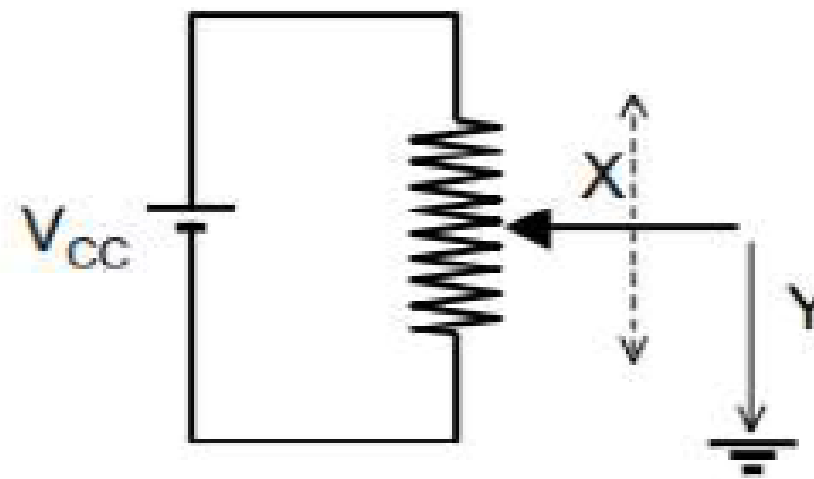


# Generalized Performance of Zero Order System

$$y(t) = k \cdot x(t) \Rightarrow \frac{Y(s)}{X(s)} = k$$

## Example of a zero-order sensor

- A potentiometer used to measure linear and rotary displacements
  - This model would not work for fast-varying displacements

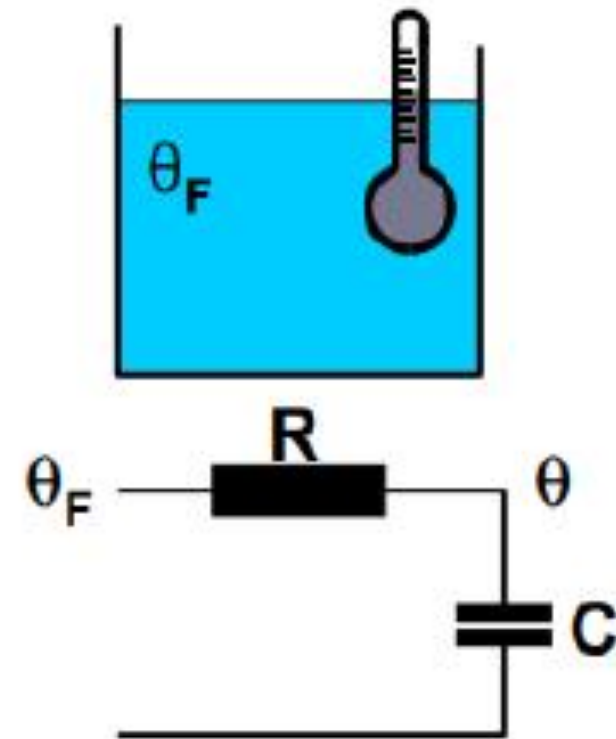




# Generalized Performance of First Order System

$$a_1 \frac{dy}{dt} + a_0 y(t) = x(t) \Rightarrow \frac{Y(s)}{X(s)} = \frac{1}{a_1 s + a_0} = \frac{k}{\tau s + 1}$$

## Example



$$\theta(s) = \frac{\theta_F(s)}{(RCs + 1)} \Rightarrow \theta(t) = \theta_F (1 - e^{-t/RC})$$

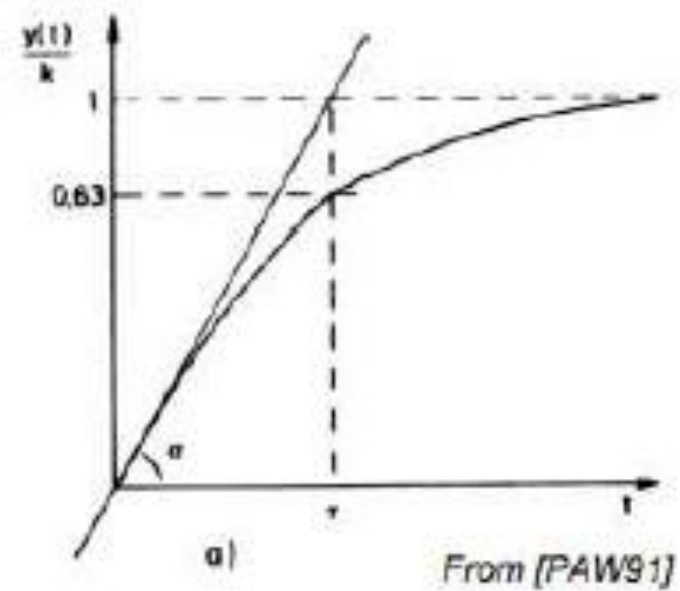




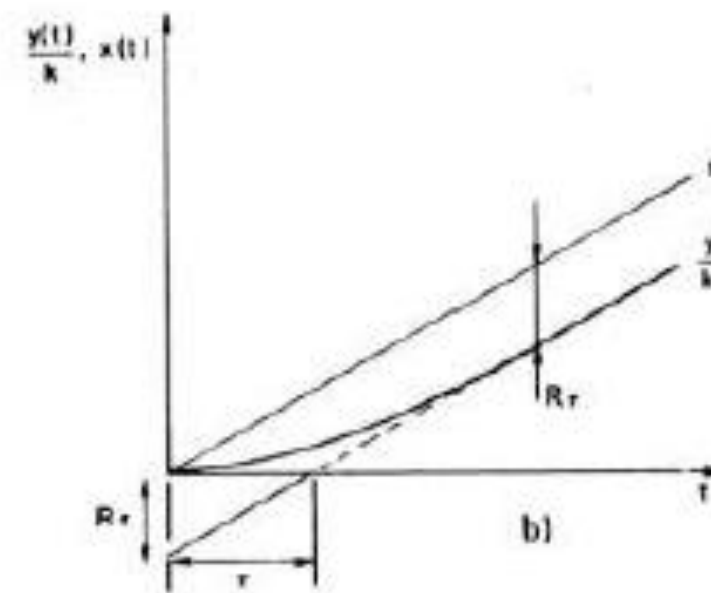
# Response of Transducer with time varying input



## Step response

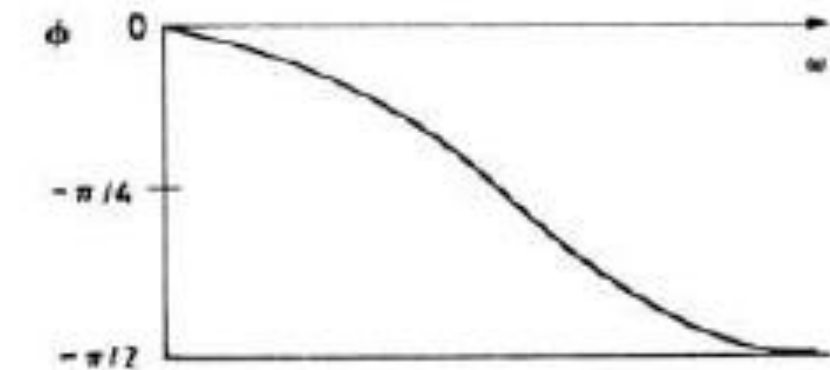
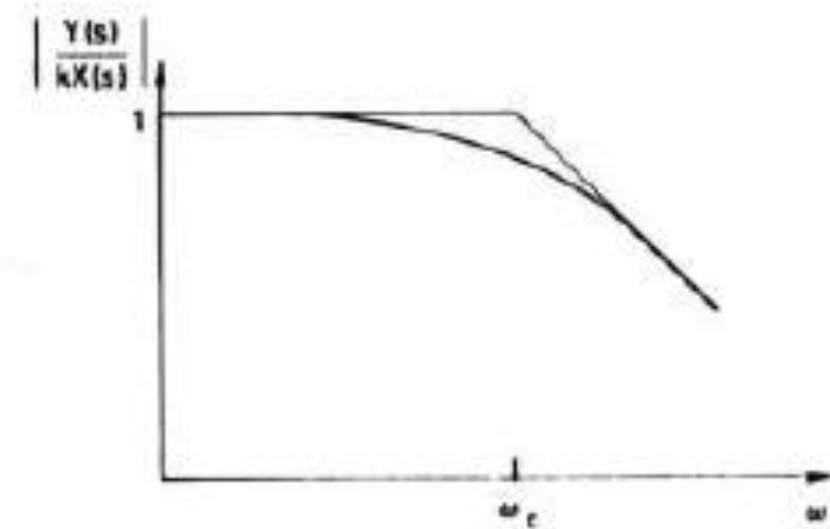


## Ramp response



## Frequency response

- Corner frequency  $\omega_c = 1/\tau$
- Bandwidth





# *Introduction to Second Order System*

$$a_2 \frac{d^2y}{dt^2} + a_1 \frac{dy}{dt} + a_0 y(t) = x(t) \Rightarrow \frac{Y(s)}{X(s)} = \frac{1}{a_2 s^2 + a_1 s + a_0}$$

We can express this second-order transfer function as

$$\frac{Y(s)}{X(s)} = \frac{k\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

$$\text{with } k = \frac{1}{a_0}, \zeta = \frac{a_1}{2\sqrt{a_0 a_2}}, \omega_n = \sqrt{\frac{a_0}{a_2}}$$



*Thank You*