



# **SNS COLLEGE OF TECHNOLOGY**

**(An Autonomous Institution)**



**COIMBATORE-35**

**Accredited by NBA-AICTE and Accredited by NAAC – UGC with A+ Grade  
Approved by AICTE, New Delhi & Affiliated to Anna University, Chennai**

**DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING**

**COURSE NAME: 19EET207/ SYNCHRONOUS AND INDUCTION  
MACHINES**

**II YEAR / IV SEMESTER**

**Unit 1 – SYNCHRONOUS GENERATOR**

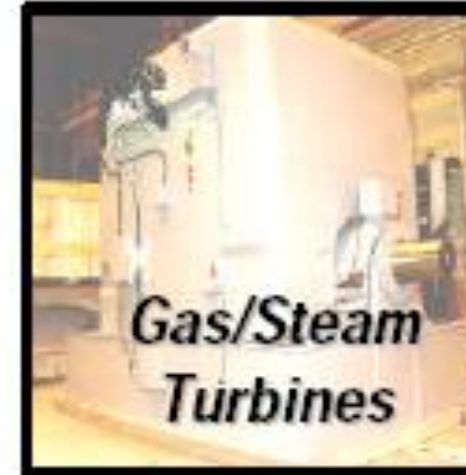
**Topic 7: Voltage regulation - EMF, MMF, and ZPF methods**





# GUESS THE TOPIC NAME...

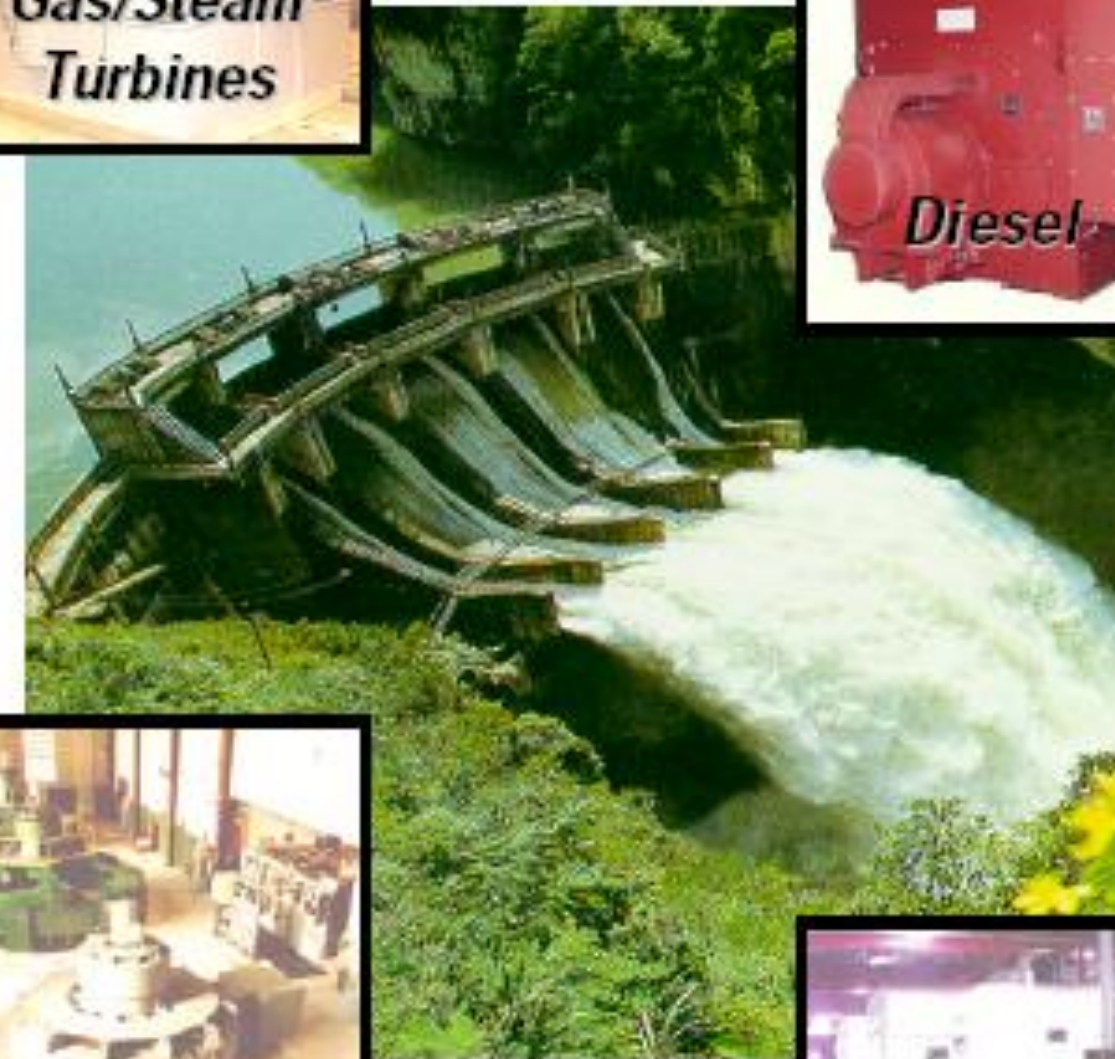
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Gas/Steam  
Turbines



Diesel



Hydro



Special  
Applications

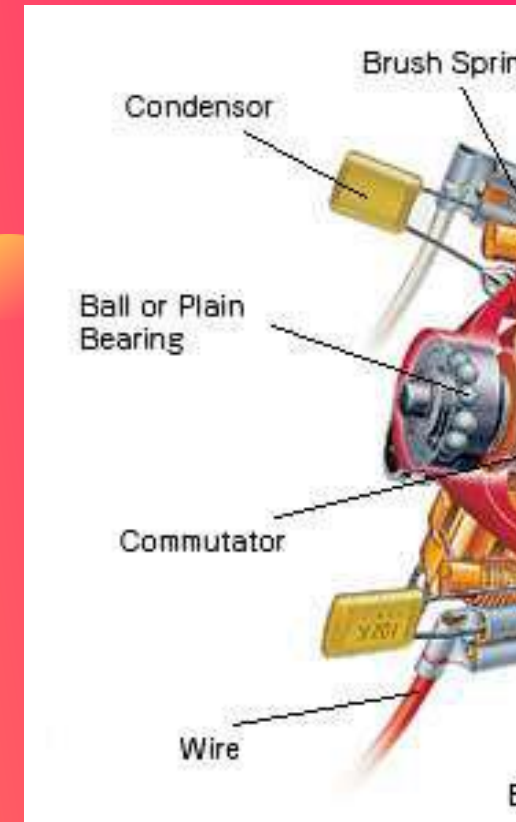


# VOLTAGE REGULATION

Voltage Regulation of an alternator is defined as the change in terminal voltage from **NO load** to **full load** divided by **full-load voltage**.

$$\% \text{ Voltage Regulation} = \frac{\text{NO load voltage} - \text{Full load voltage}}{\text{Full load Voltage}} \times 100$$

$$\% \text{ Voltage Regulation} = \frac{E_0 - V}{V} \times 100$$





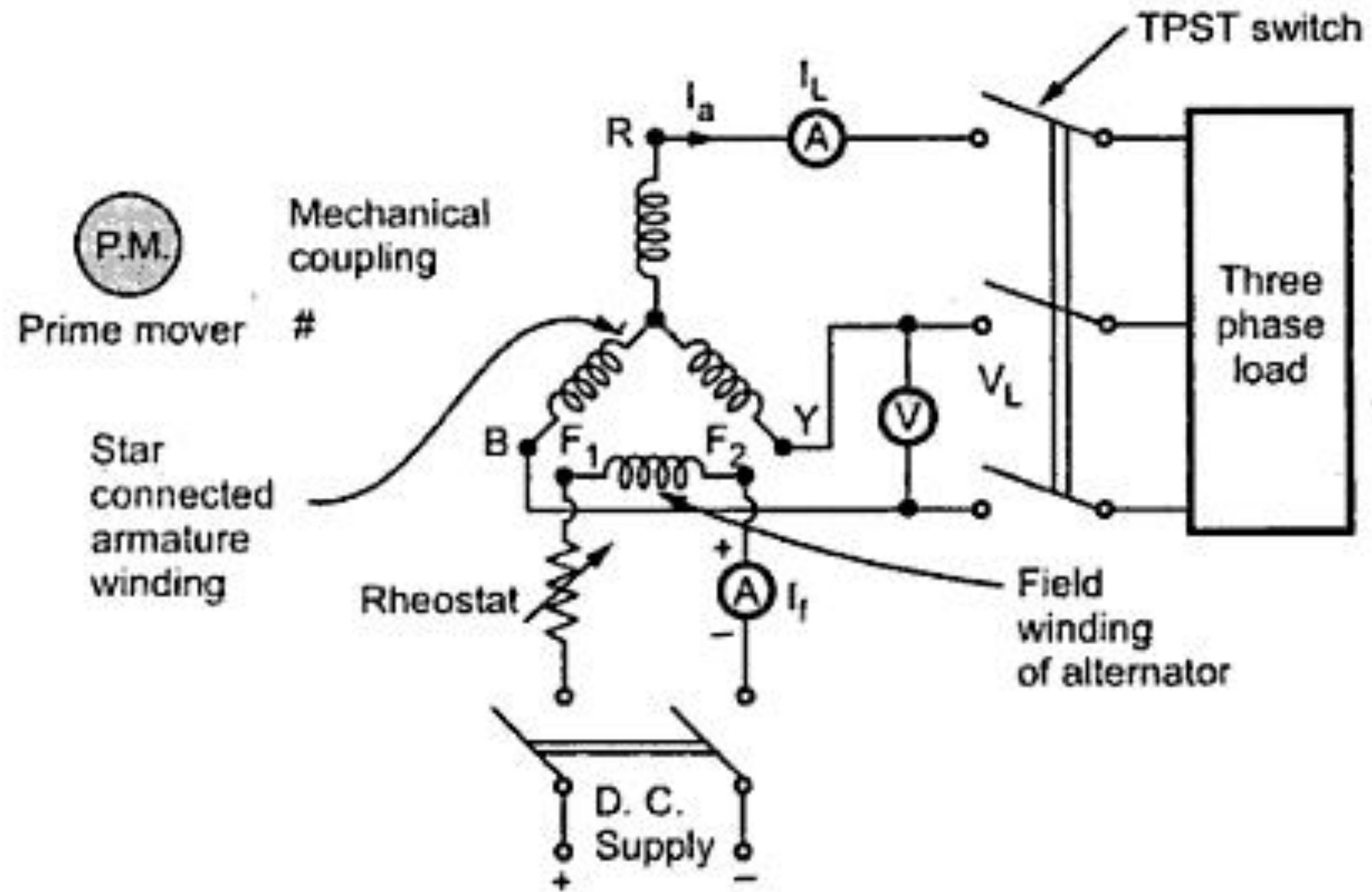
# Methods

There are different methods available to determine the voltage regulation of an alternator,

1. Direct loading method
2. Synchronous impedance method or E.M.F. method
3. Ampere-turns method or M.M.F. method
4. Zero power factor method or Potier triangle method
5. ASA modified from of M.M.F. method
6. Two reaction theory



# Direct loading method





# Direct loading method

The star connected **armature** is to be connected to a **three phase load**. The **field winding** is excited by separate **d.c. supply**.

To **control the flux** i.e. the current through field winding, a **rheostat is inserted in series** with the field winding.

The **prime mover** drives the alternator at its **synchronous speed**.

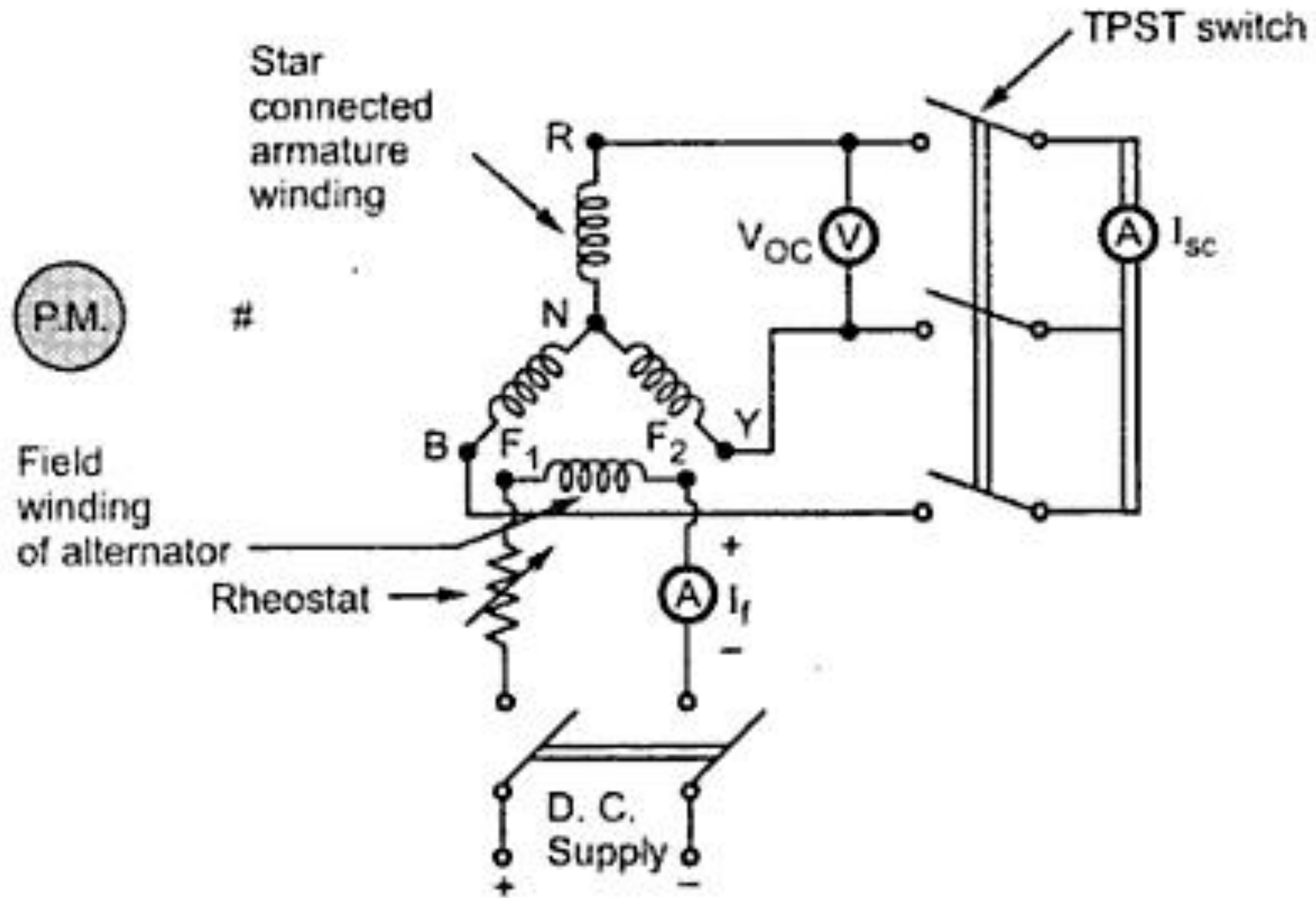
$$E_{ph} \propto \Phi \text{ ..... (From e.m.f. equation)}$$

$$\% \text{ Reg} = \frac{E_{ph} - V_{ph}}{V_{ph}} \times 100$$

For **high capacity** alternators, that much **full load can not** be simulated or directly connected to the alternator. Hence method is **restricted only for small capacity alternators**.



# Synchronous Impedance Method or E.M.F. Method





# Synchronous Impedance Method or E.M.F. Method

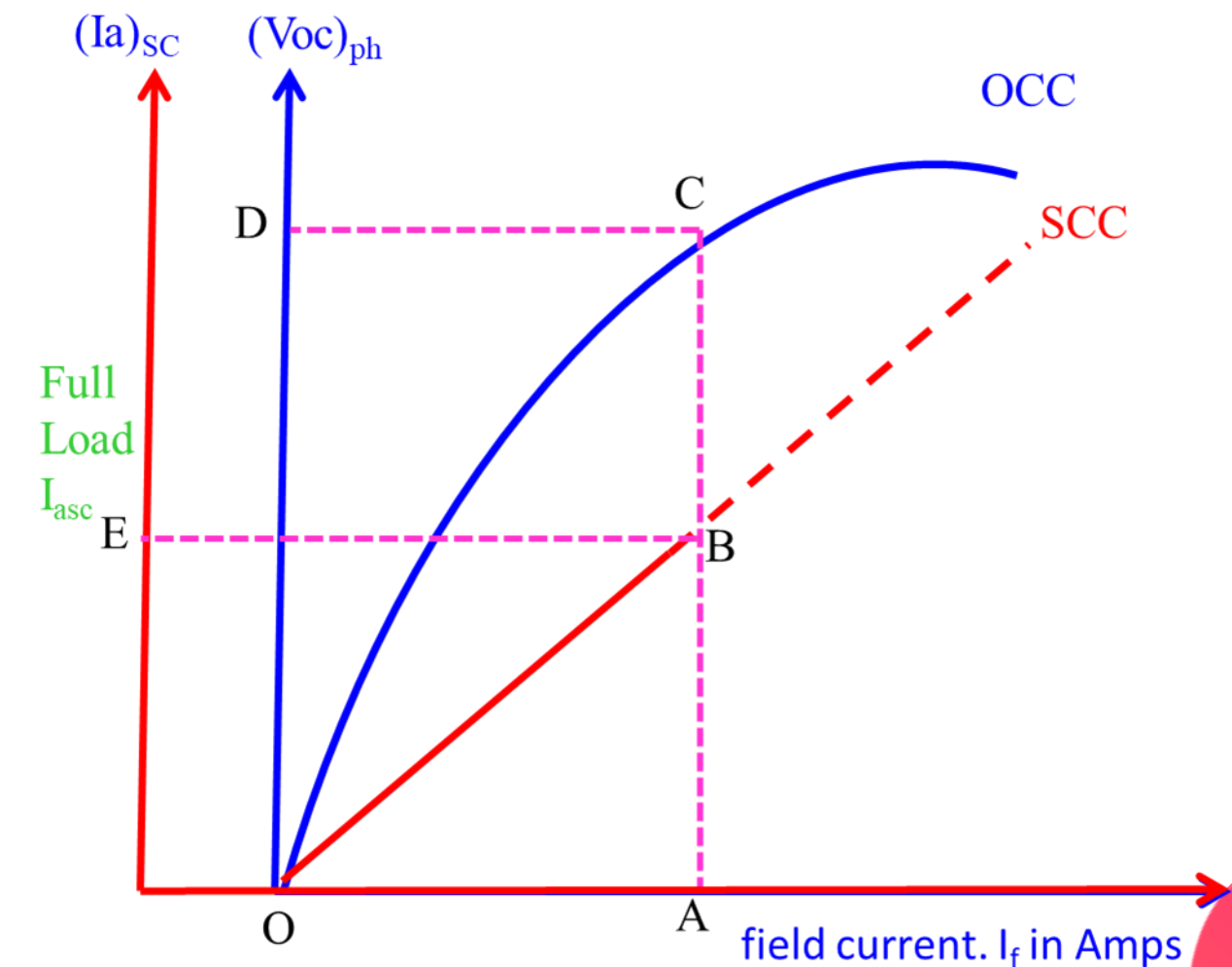
The method requires following data to calculate the regulation.

1. The **armature resistance per phase ( $R_a$ )**.
2. Open circuit characteristics which is the graph of **open circuit voltage** against the **field current**. This is possible by conducting **open circuit test** on the alternator.
3. Short circuit characteristics which is the graph of **short circuit current** against **field current**. This is possible by conducting **short circuit test** on the alternator.

$Z_s$  is calculated.

$R_a$  measured and  $X_s$  obtained.

For a given armature current and power factor,  $E_{ph}$  determined - regulation is calculated.







# Synchronous Impedance Method or E.M.F. Method

Synchronous Impedance

$$Z_s = \frac{(V_{oc})_{ph}}{I_{asc}}$$

$$Z_s = \frac{\text{Phase emf on Open Circuit}}{\text{Phase Current on Short Circuit}}$$

$$Z_s = \frac{OD (V_{oc})_{ph}}{OE (I_{asc})}$$

Regulation Calculation

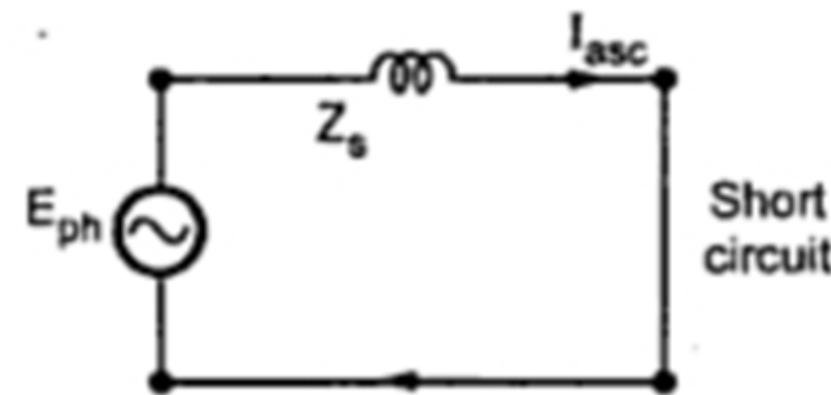
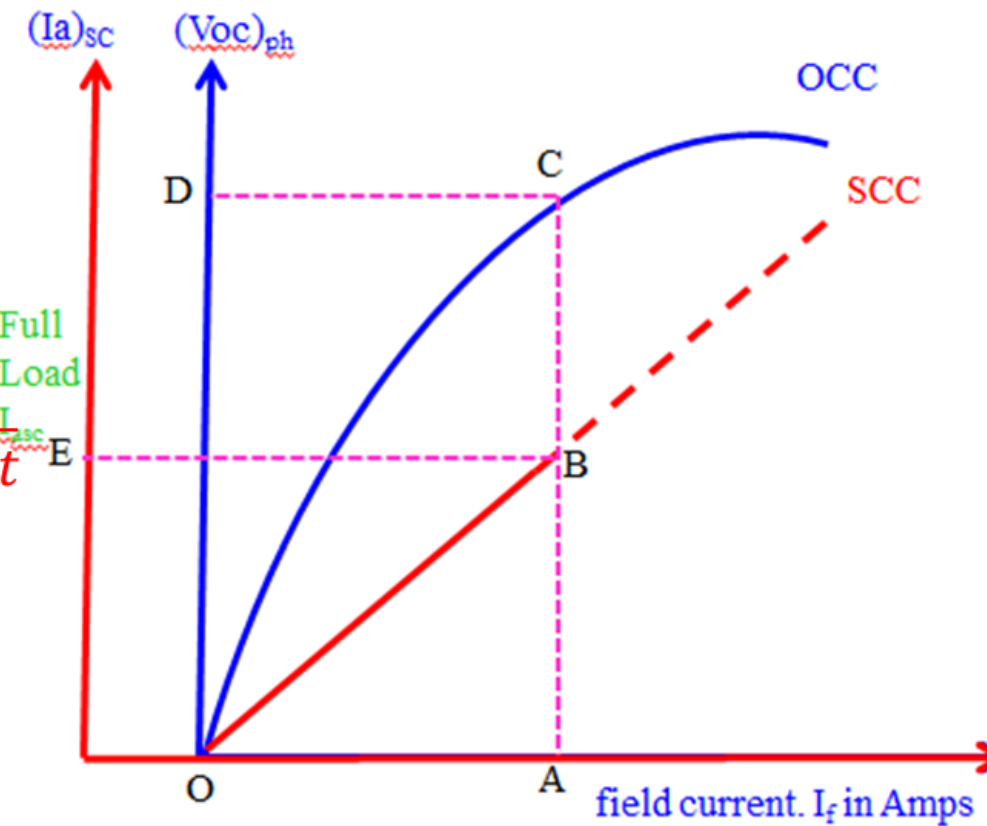
$$Z_s = \sqrt{(R_a)^2 + (X_s)^2}$$

$X_s$

$$X_s = \sqrt{(Z_s)^2 - (R_a)^2}$$

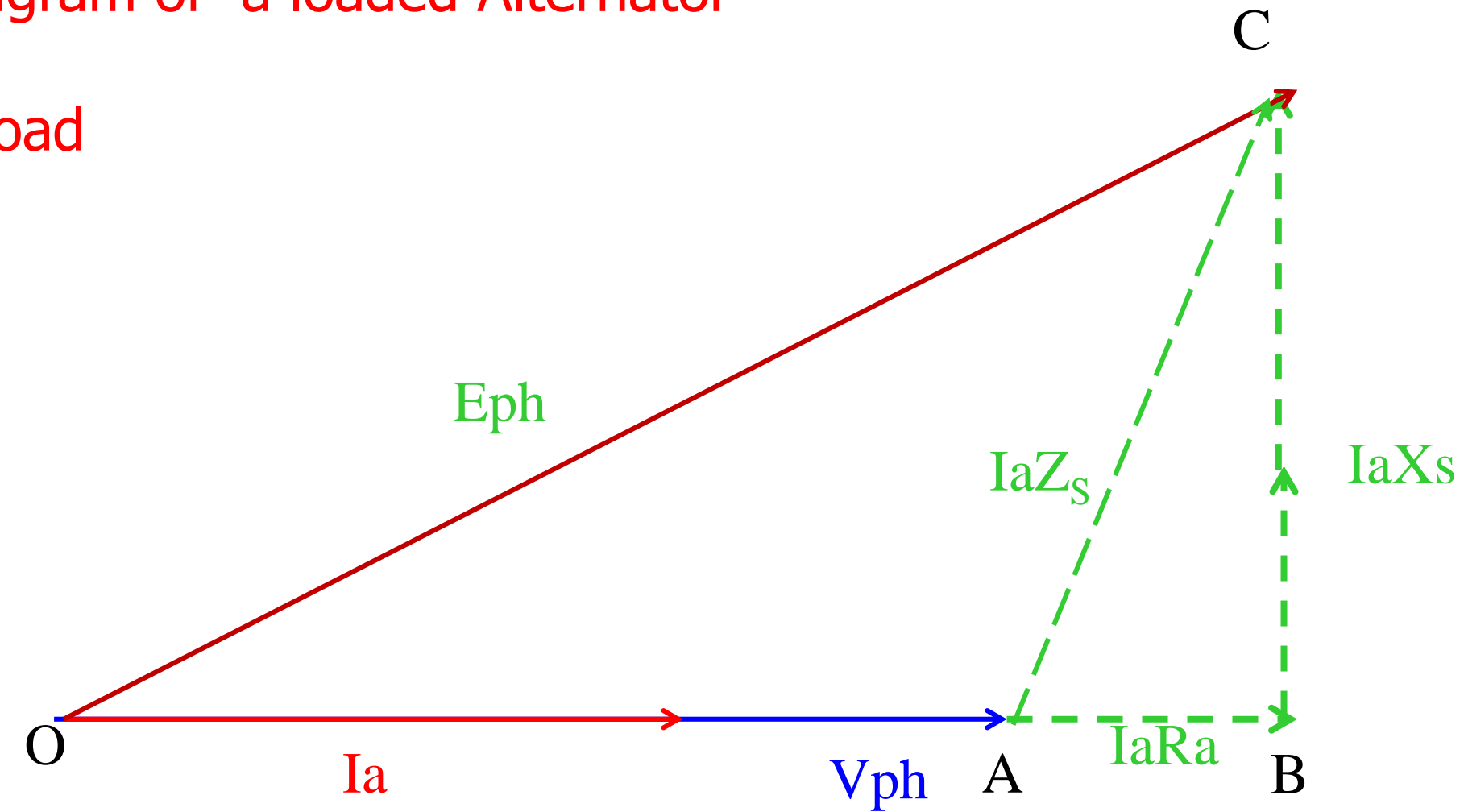
$$E_{ph} = \sqrt{(V_{ph} \cos \Phi + I_a R_a)^2 + (V_{ph} \sin \Phi \pm I_a X_s)^2}$$

$$\% \text{ Regulation} = \frac{E_{ph} - V_{ph}}{V_{ph}} \times 100$$



# Phasor Diagram of a loaded Alternator

Unity PF Load



Reference as Voltage (V)

OA –  $V_{ph}$

AB –  $I_a R_a$

BC –  $I_a X_s$

AC –  $I_a Z_s$

OC –  $E_{ph}$

Consider  $\Delta$  OBC

$$(OC)^2 = (OB)^2 + (BC)^2$$

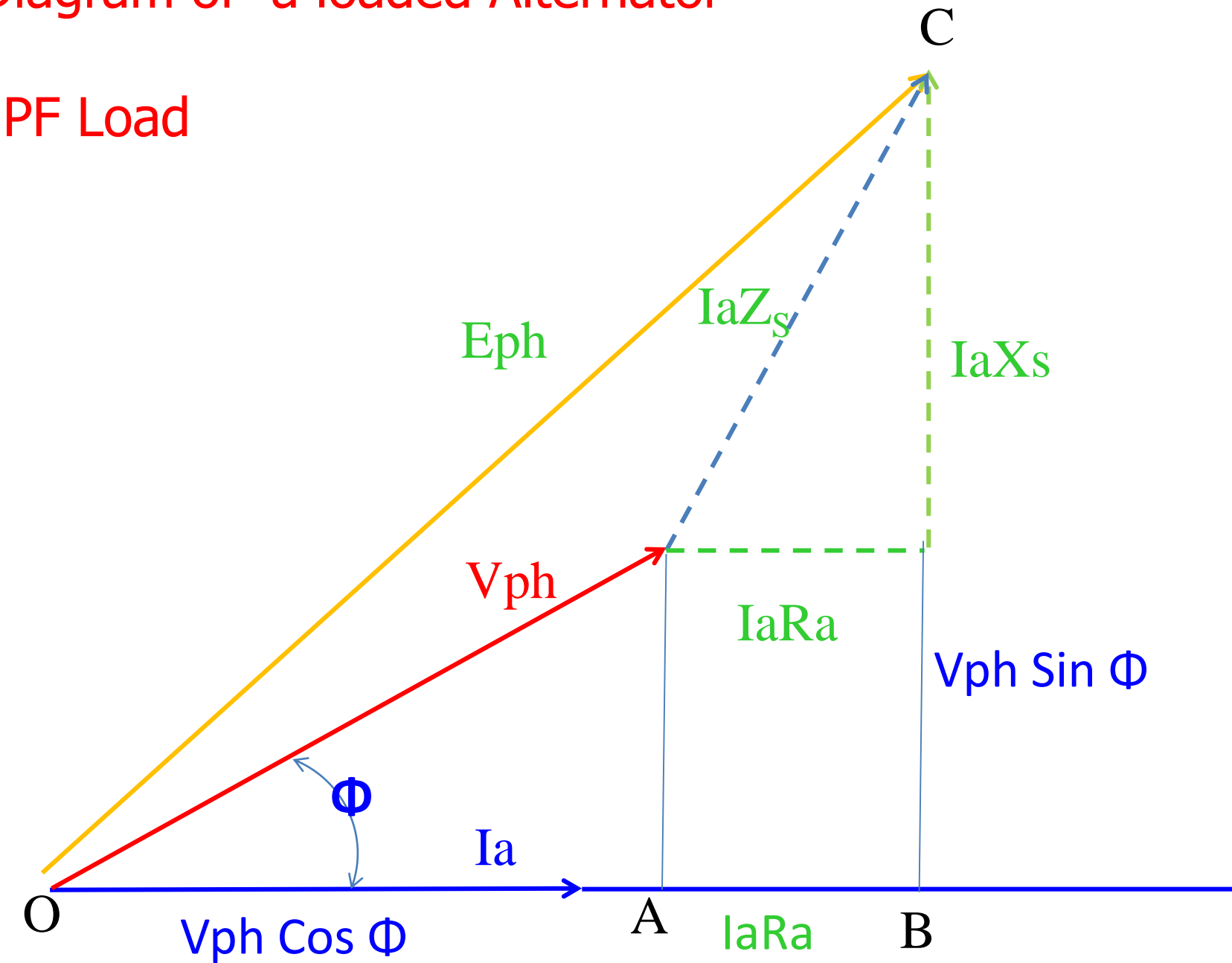
$$(E_{ph})^2 = (OA + AB)^2 + (BC)^2$$

$$(E_{ph})^2 = (V_{ph} + I_a R_a)^2 + (I_a X_s)^2$$

$$E_{ph} = \sqrt{(V_{ph} + I_a R_a)^2 + (I_a X_s)^2}$$

## Phasor Diagram of a loaded Alternator

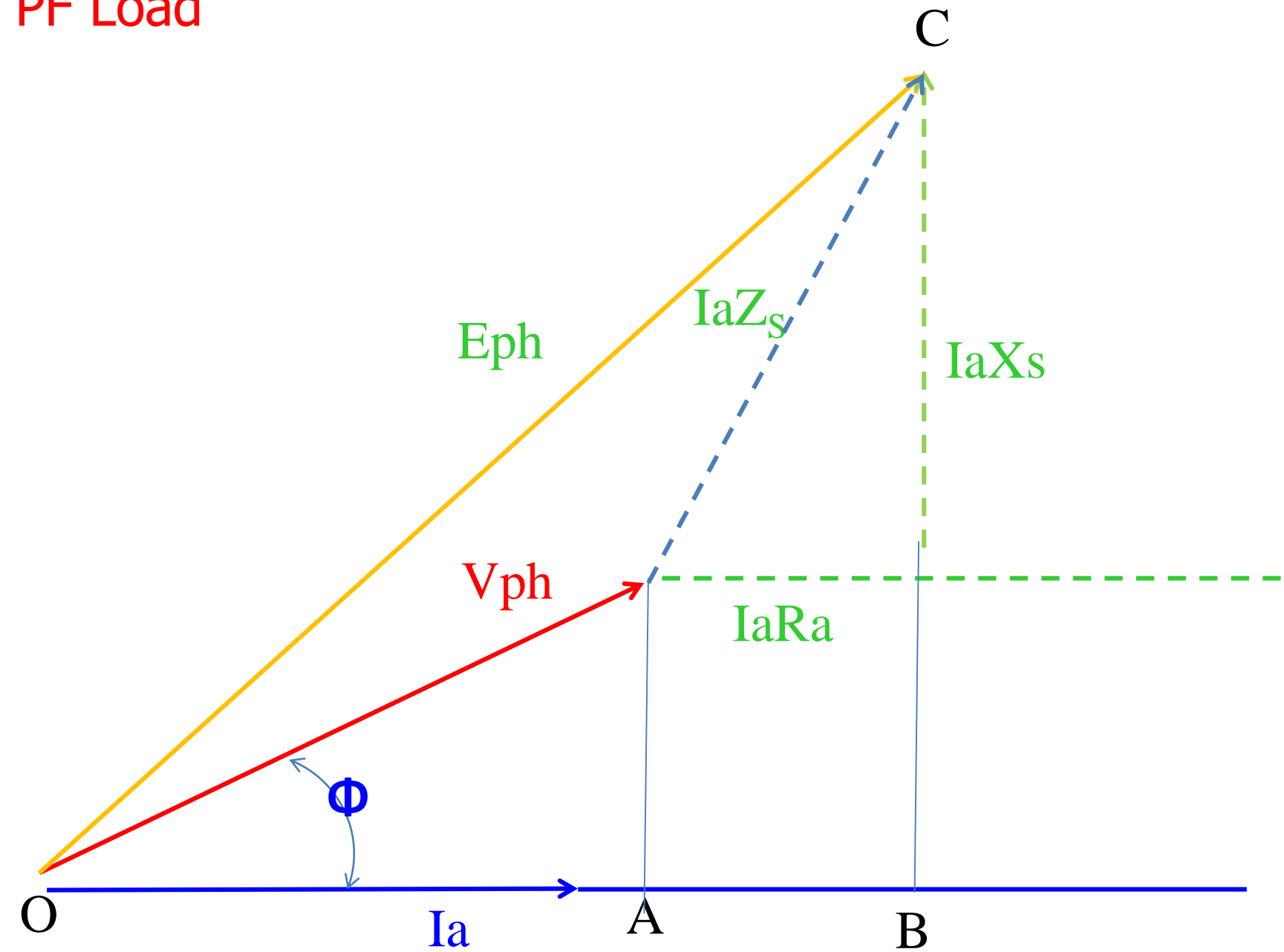
Lagging PF Load



$$E_{ph} = \sqrt{(V_{ph} \cos \Phi + I_a R_a)^2 + (V_{ph} \sin \Phi + I_a X_s)^2}$$

## Phasor Diagram of a loaded Alternator

Leading PF Load



$$E_{ph} = \sqrt{(V_{ph} \cos \Phi + I_a R_a)^2 + (V_{ph} \sin \Phi - I_a X_s)^2}$$



# Synchronous Impedance Method or E.M.F. Method



## Advantages of Synchronous Impedance Method

The main advantages of this method is the value of **synchronous impedance  $Z_s$**  for **any load condition** can be calculated.

Regulation of the alternator at **any load condition and load power factor** can be determined.

Actual **load need not be connected** to the alternator

This method can be **used for very high capacity alternators**

## Limitations of Synchronous Impedance Method

The **main limitation** of this method is that this method gives **large values of synchronous reactance**.

This leads to **high values of percentage regulation** than the actual results.

Hence this method is called **pessimistic method**.



# MMF method (Ampere turns method)



This method of determining the regulation of an alternator is also called **Ampere-turn method or Rothert's M.M.F. method.**

The method is based on the results of **open circuit test and short circuit test** on an alternator.

For any synchronous generator i.e. alternator, it requires **M.M.F.** which is product of **field current** and turns of **field winding** for **two separate purposes.**

1. It must have an **M.M.F.** necessary to **induce the rated terminal voltage** on open circuit.
2. It must have an **M.M.F. equal and opposite** to that of **armature reaction m.m.f.**



# MMF method (Ampere turns method)



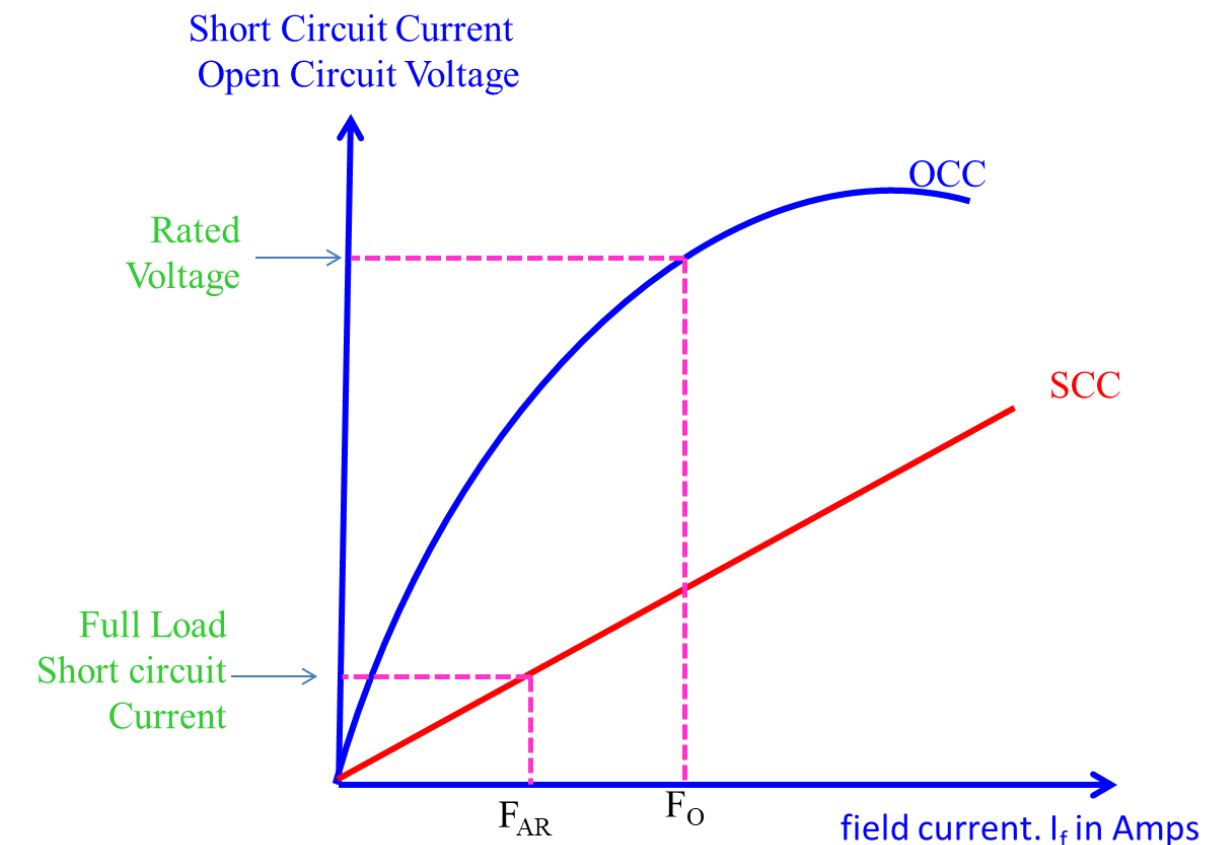
## OC & SC tests conducted

field currents

$I_{f1}$  (field current required to **produce a voltage** of  $(V_{ph} + I_{aph} R_a \cos\Phi)$  on **OC**)

$I_{f2}$  (field current required to produce the given **armature current** on SC) are added at an angle of  $(90 \pm \Phi)$ .

For this total field current,  $E_{ph}$  found from OCC and regulation calculated.



## Zero Power Factor Method (ZPF Method) or Potier method

This method is also called **Potier method**.

In the operation of any alternator, Voltage drop occurs in

**Armature resistance drop ( $IR_a$ )**

**Armature leakage reactance drop  $IX_L$**

Mainly due  
EMF quantity

**Armature reaction.**

→ is basically **M.M.F.** quantity

In the **synchronous impedance** method all the quantities are treated as **E.M.F. quantities**

In the **MMF Method** all the quantities are treated as **M.M.F. quantities**

The ZPF method is based on the Separation of  
**Armature leakage reactance ( $X_L$ )** and  
**Armature reaction effect**

The armature leakage reactance  $X_L$  is called **Potier reactance**



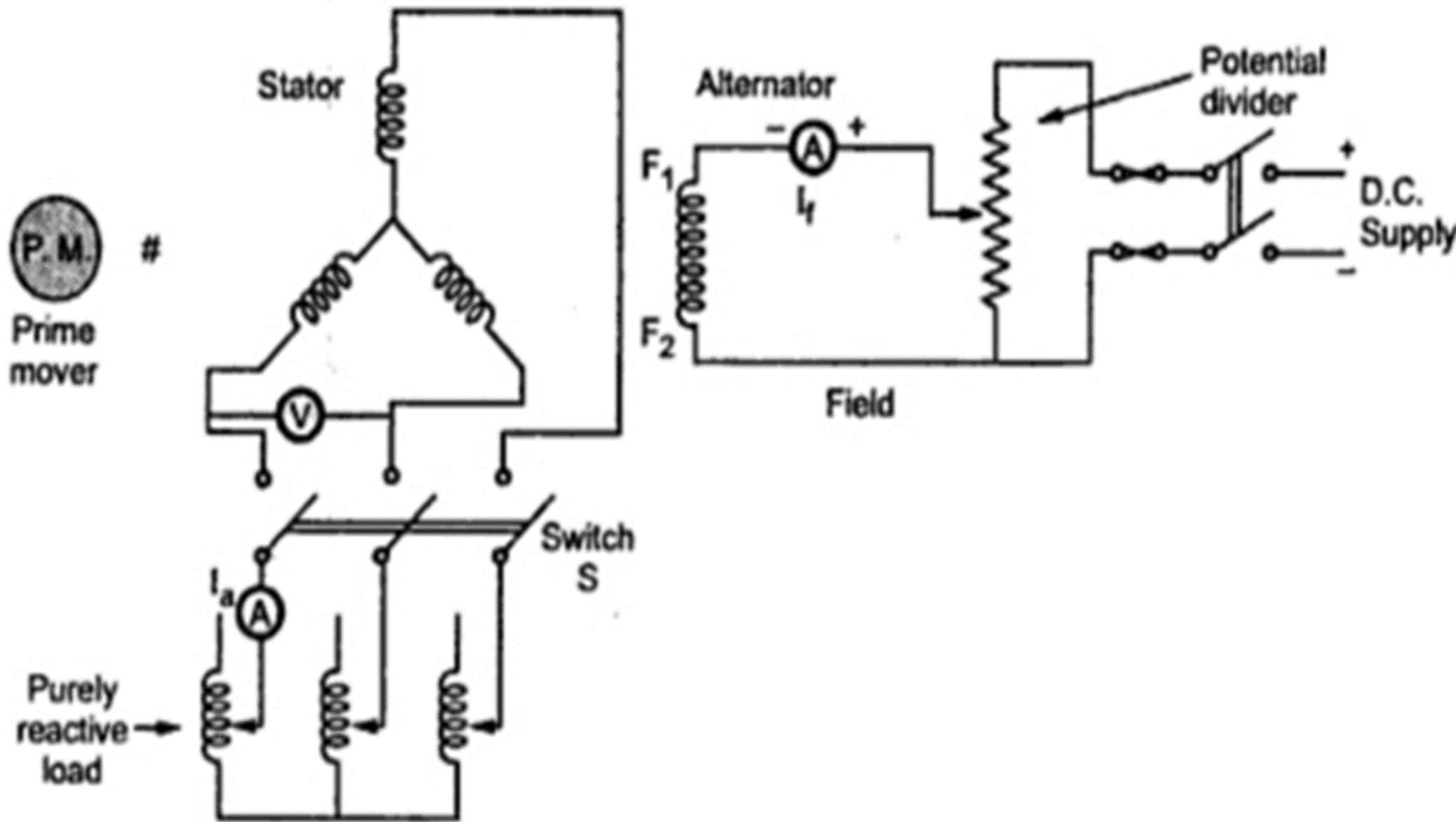


# Zero Power Factor Method (ZPF Method) or Potier method



To determine **armature leakage reactance (EMF)** and **armature reaction (MMF) separately**, two tests are performed on the alternator

1. Open circuit test
2. Zero power factor test



## Open circuit test

Switch Open

P.M. to drive  $N_s$

Potential Divider from 0 to Rated Value

## Zero power factor test

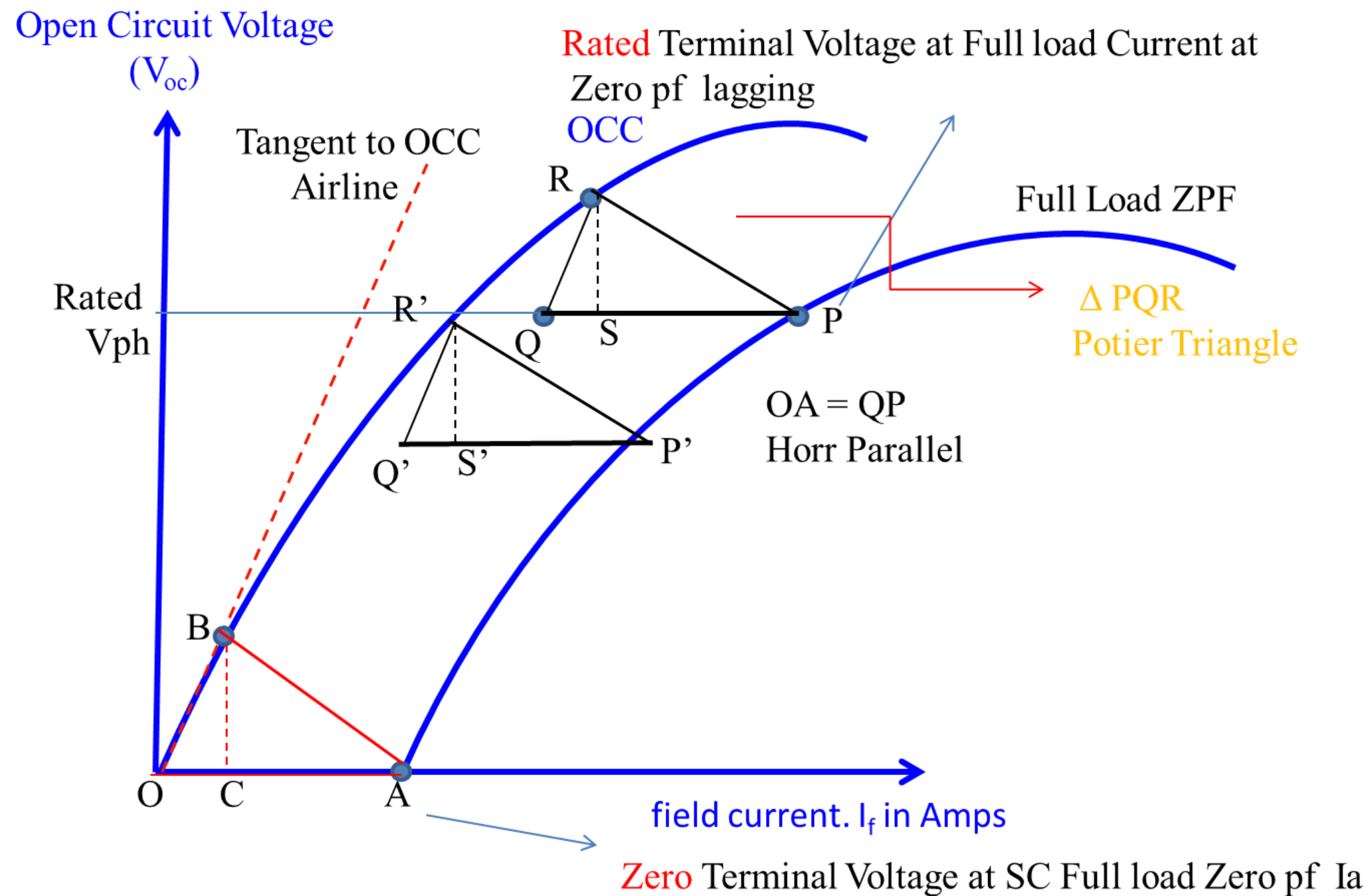
Switch Closed

Purely Inductive Load

Purely Inductive Load has PF  $\cos 90^\circ$



# Zero Power Factor Method (ZPF Method) or Potier method



RS Voltage Drop Armature Leakage Reactance ( $IX_L$ )

PS Gives  $I_f$  necessary to overcome Demagnetizing Armature Reaction

SQ rep  $I_f$  required to induce an EMF balancing of leakage reactance (RS)



# SUMMARY

Voltage regulation - EMF, MMF, and ZPF methods



KEEP  
LEARNING..  
**Thank u**

SEE YOU IN NEXT CLASS