

#### **SNS COLLEGE OF TECHNOLOGY**



#### Coimbatore-35 An Autonomous Institution

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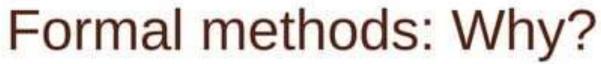
#### **DEPARTMENT OF INFORMATION TECHNOLOGY**

19CSE303 – ARTIFICIAL INTELLIGENCE

#### UNIT IV - UNCERTAIN KOWLEDGE AND REASONING

TOPIC - Temporal Model







REAL DEVELOPMENT IDEAL DEVELOPMENT Specification + ∆Errors Design Coding Testing Product

+ \Delta Errors + ∆Bugs

Limited Coverage

with safety issues





#### Formal methods: Where?



- An Investigation of Therac-25 Accidents [Leveson, Turner, 93]
- Ariane 5 Flight 501 Failure, Report by Inquiry Board [Lions, 96]
- Slammer worm crashed Ohio nuke plant network, News Report [http://www.securityfocus.com/news/6767, 03]



# Sentences (Syntax) and Models (Semantics)



- "Every PhD student must have an advisor who is a member of faculty"
- $F = \forall x \cdot phd\text{-student}(x) \Rightarrow \exists y \cdot advisor\text{-of}(y, x) \land faculty(y)$
- What does F mean?
  - Classical Interpretation A mathematical structure with:
  - advisor-of mapped to a binary relation on the structure
  - phd-student, faculty mapped to unary relations
  - Logical symbols (∧, ⇒) have fixed interpretation
  - Quantifiers (∀,∃) range over elements of the underlying set
- Model of F = a satisfying interpretation for F



## Fundamental reasoning tasks

M satisfies F? Model checking problem

? satisfies F Satisfiability problem

\* satisfies F Validity problem

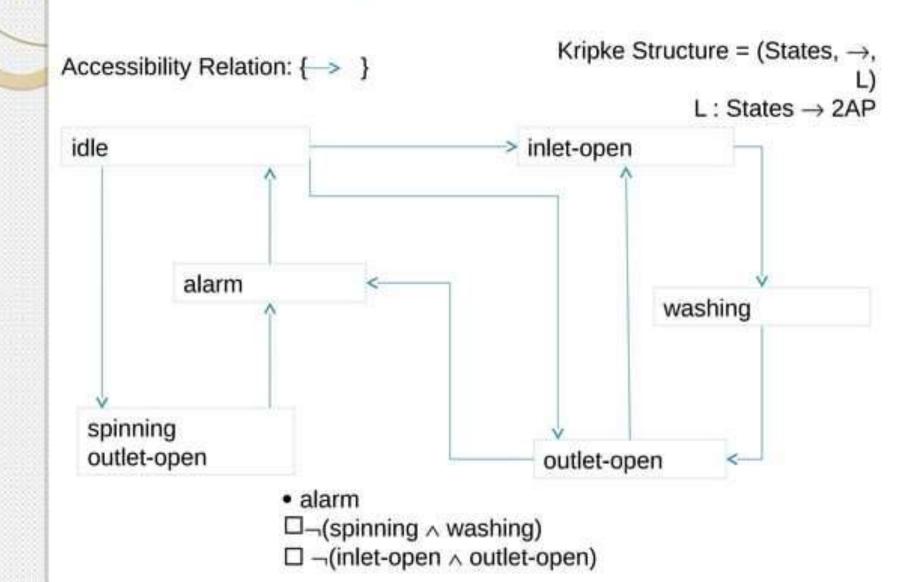
•  $\{a: M \models F(a)\}$  Formula (query) evaluation

Note: |= denotes *satisfies* relation

## Modal Logic

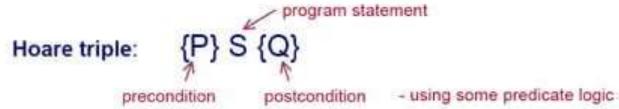
- Modalities: Necessity, knowledge, belief, obligation, tense
  - Symbolic Logic [Lewis,32]
- Possible World Semantics
  - Kripke Structure
- Temporal Logic
  - Time and Modality [Prior,57]
  - Temporal modalities: always (□), eventually (•)

# Possible Worlds & Kripke Structure for a washing machine





#### Verification: Sequential Programs



- Assigning Meanings to Programs [Floyd,67]
- An Axiomatic basis for Computer
   Programming [Hoare, CACM69] (Hoare Logic)
- Guarded commands, non-determinism and formal derivation of programs [Dijstra,75] (GCL)

### Hoare Logic

(Assignment Axiom)

$${Q[E/id]} id=E; {Q}$$

(Conditional Rule)

$$\{P \land E\} S_1 \{Q\} \{P \land \neg E\} S_2 \{Q\}$$

(Sequencing Rule)

$$\{P\} S_1 \{R\} S_2 \{Q\}$$
  
 $\{P\} S_1 S_2 \{Q\}$ 

(Pre-strengthening, Post-weakening)

Proof Tableaux

$$\{P_1\}$$
  $c_1$ ;  $\{Q_1\}$   $\{Q_2\}$   $\{Q_2\}$ 

$$\{P_n\}$$
  $c_n$   $\{c_n\}$ 

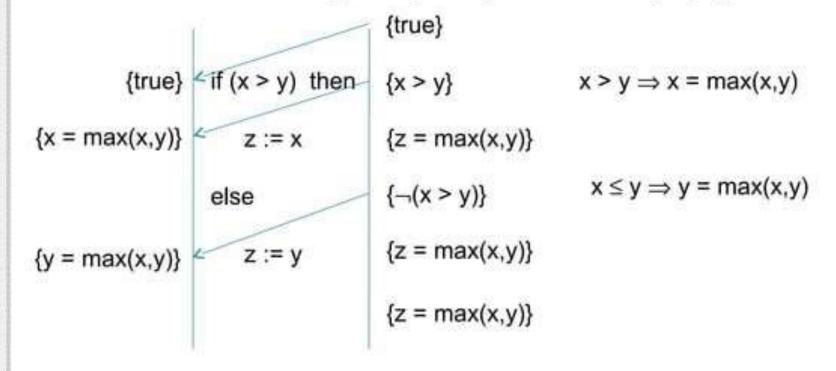




#### Hoare Logic Example

P = if (x > y) then z := x else z := y

Prove that: {true} P {z = max(x,y)}







#### Concurrency

- Simple pre-condition/post-condition assertions insufficient
  - Deadlocks, Data races, Starvation!
  - Need a language for expressing concurrency properties
- Cannot ignore intermediate steps!
  - P; Q: Intermediate states of P & Q do not interleave/interact
  - P || Q : Intermediate states interleave/interact (in exponential number of ways)



# Specifying properties of concurrent systems

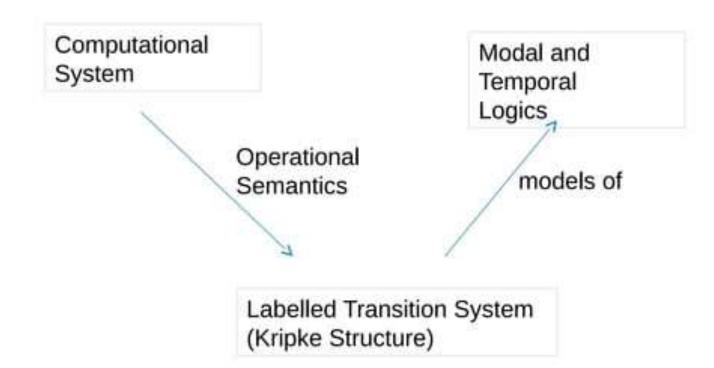


- Language: Temporal Logic
  - The Temporal Logic of Programs [Pnueli,77] (Linear Temporal Logic)
- Safety
  - something bad will never happen:
  - □ ¬(spinning ∧ washing)
- Liveness
  - Something good will eventually happen:
  - alarm
- Fairness
  - Always something good will eventually happen
  - □ idle





### Why Temporal Logics?



[Stirling03] http://www.fing.edu.uy/inco/eventos/wssa/



#### Producer-Consumer with 1-buffer

Producer

wtp: while (!isempty);

csp: buf = produce();

flp: isempty = false;

Consumer

wtc: while (isempty);

csc: consume(buf);

flc: isempty = true;

## State space for 1-buffer system

```
States = control state \times data state
= \{wtp, csp, flp\} \times \{wtc, csc, flc\} \times \{da\} \times \{em\}\}
```

wt:wait

cs : critical section

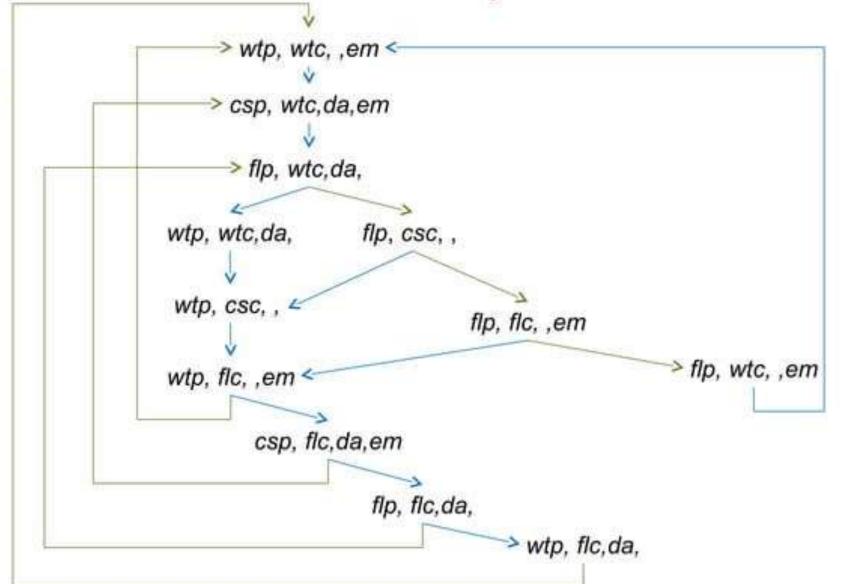
fl : flag update

da : buf has data available

em: isempty is true

e.g., (wtp, csc, ,em) ∈ States

### LTS for 1-buffer system





#### Temporal Properties for 1-buffer system

- Safety:  $\Box \neg (csp \land csc)$ 
  - Producer and Consumer will never be in the CS at the same time
- Liveness: (da ∧ ¬ em)
  - Eventually data will become available and empty flag reset
- Fairness: □
   csp
  - Producer is always given a fair chance to produce





#### Model Checking

- Model checking: M |= F?
- Design & Synthesis of synchronization skeletons using branching temporal logic [Clarke &Emerson, 81]
- Specification & Verification of Concurrent Systems in Cesar [Queille & Sifakis, 82]
- Automatic Verification of Finite-State Concurrent Systems using Temporal Logic Specifications [Clarke, Emerson, Sistla, TOPLAS86]





### Computations of LTS

- Unfold LTS → Infinite tree of computations
  - Interleaved Semantics
  - Concurrency as non-determinism

- View of computations: Linear vs Branching
  - Linear Temporal Logic
  - Computational Tree Logic

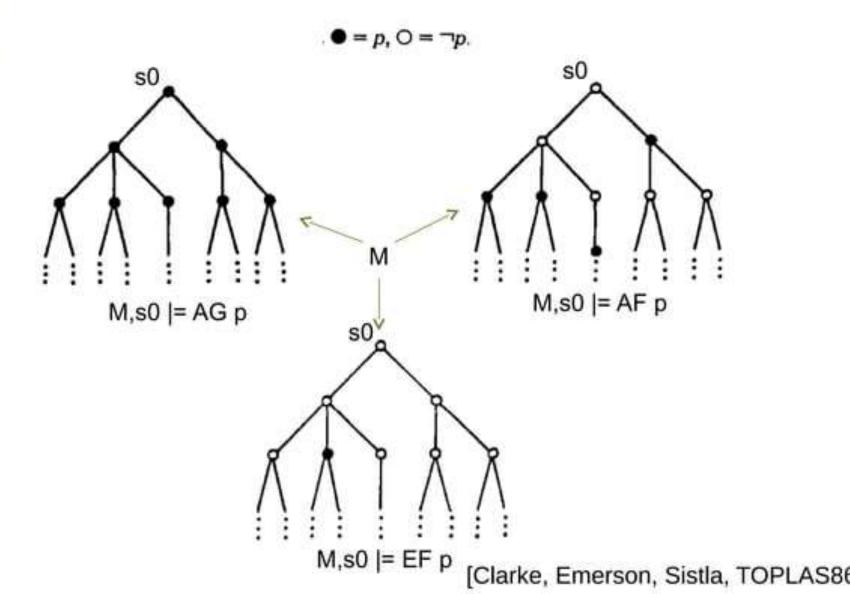




### Computational Tree Logic

- Path quantifier
  - A: All paths (inevitably)
  - E: there Exists a path (possibly)
- Temporal operator
  - X: neXt state
  - F: some Future state (eventually)
  - G: Globally; all future states
  - U: Until
- e.g., AF: for all paths eventually, EG: for some path globally

#### **CTL** semantics







#### CTL examples

It is possible to get to a state where started holds, but ready doesn't: EF (started  $\land \neg ready$ ).

For any state, if a request (of some resource) occurs, then it will eventually be acknowledged:

AG (requested  $\rightarrow AF$  acknowledged).

From any state it is possible to get to a **restart** state: AG (EF restart).

A certain process is **enabled** infinitely often on every computation path: AG (AF enabled).

The lift can remain idle on the third floor with its doors closed: AG (floor3  $\land$  idle  $\land$  doorclosed  $\rightarrow$  EG (floor3  $\land$  idle  $\land$  doorclosed)).

Logic in Computer Science [Huth, Ryan, 04]





### Computational Tree Logic

```
    φ ::= T|F|p
    |¬φ|φ∧φ|φ∨φ|φ→φ
    |AX φ|EX φ
    |AF φ | EF φ
    |AG φ|EG φ
    |A [φ U φ] | E [φ U φ]
```

A: inevitably (along all paths)

E: possibly (there exists a path)

G: globally (always), F: in future (eventually)

X: neXt state, U: until





#### Model Checking

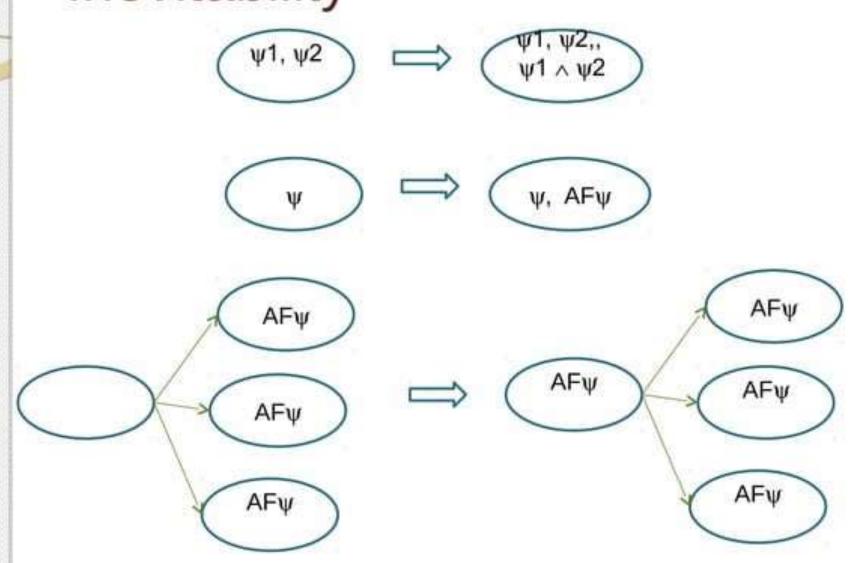
- M |= F?
- SAT(M, φ) : 2S
  - INPUT:
    - $\text{@CTL model M} = (S, \rightarrow, L)$
  - OUTPUT:
    - Set of states (⊆ S)that satisfy φ
  - Complexity: O(f . |S| . (|S| + |→|))

Logic in Computer Science [Huth, Ryan, 04]



# SAT: Conjunction & Inevitability

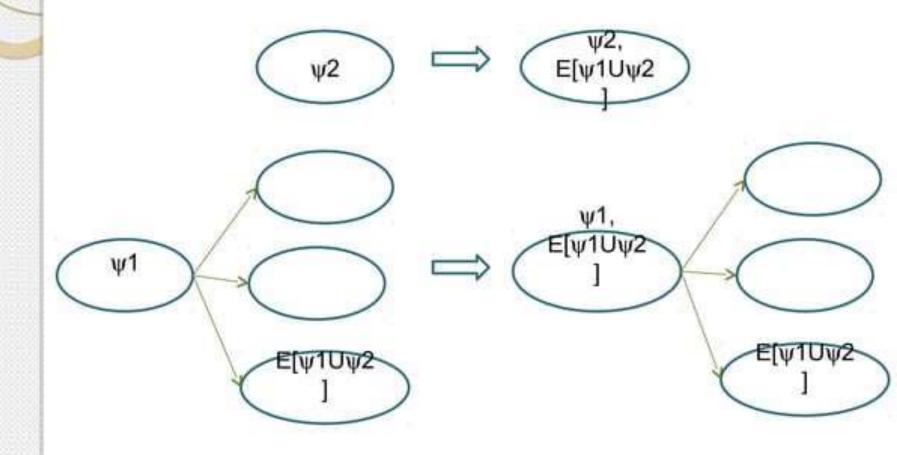








## SAT: Possibly Until







#### $SAT(\phi): 2S$

```
begin
  case(\phi)
           : return S
      : return Ø
      \neg \psi: return S – SAT(\psi)
      \phi 1 \wedge \phi 2: return SAT(\phi 1) \cap SAT(\phi 2)
      \phi 1 \lor \phi 2: return SAT(\phi 1) \cup SAT(\phi 2)
      \phi 1 \Rightarrow \phi 2: return SAT(\neg \phi 1 \lor \phi 2)
```





#### SAT (case( $\phi$ ) cont.d)

 $AF\psi$  :  $SATAF(\psi)$ 

 $E[\phi 1U\phi 2]$ : SATEU( $\phi 1, \phi 2$ )

end case

end





### SATAF(\phi)

```
function f(\phi, Y)
begin
                         begin
  Y := \emptyset;
                           if Y = \emptyset then
  repeat
                               return SAT(φ)
    X := Y;
                           else
     Y := f(\phi, Y);
                               return Y U
 until X = Y
                           pre \forall (Y)
end
                         end
```





#### Fixpoint characterization

- Consider, F: 2S → 2S
- Formula are identified with their characteristic set
  - e.g. φ denotes set of all states where φ is true
- Subsets of S (∈ 2S) form complete lattice
  - Partial order: ⊆, Join: ∪, Meet: ∩
- Knaster-Tarski theorem
  - "Monotone functions on a complete lattice possess least and greatest fixpoints": A lattice-theoretical fixpoint theorem and its applications [Tarski,55]



## Fixpoint characterization: Eventually, Until

• EF $\phi$  =  $\mu$ Z.  $\phi$   $\vee$  EX Z

• AF $\phi$  =  $\mu$ Z.  $\phi \vee$  AX Z

•  $E[\psi 1 \cup \psi 2] = \mu Z$ .  $\psi 2 \vee (\psi 1 \wedge EX Z)$ 

•  $A[\psi 1 \cup \psi 2] = \mu Z$ .  $\psi 2 \vee (\psi 1 \wedge AX Z)$ 



### Fixpoint characterization: globally

•  $AG\phi = \nu Z.\phi \wedge AX Z$ 

• EG $\phi$  =  $\nu$ Z. $\phi \wedge$ EX Z





#### LTL Model checking

- The complexity of propositional linear temporal logics [Sistla, Clarke, 85]
- Checking that finite state concurrent programs satisfy their linear specification, [Lichtenstein, Pnueli, POPL85]
- An automata-theoretic approach to automatic program verification [Vardi, Wolper, 86]
  - LTL to Buchi Automata





#### State explosion

- The state explosion problem [Clarke, Grumberg, 87]
  - Number of concurrent processes
  - Number of variables
- Partial-order reduction
  - An Introduction to Trace Theory [Mazurkiewicz,95]
- Symbolic Model Checking: 1020 states and beyond [Burch, Clarke, McMillan, Dill, Hwang, 92]
  - OBDD: Ordered Binary Decision Diagrams [Bryant,86]
  - μ-Calculus: Finiteness is μ-ineffable [Park,74]
- Abstraction
- Combining theorem-proving & model checking
- On-the-fly model checking





#### Some Tools

- SPIN/Promela
  - http://spinroot.com

- Java Pathfinder
  - http://javapathfinder.sourceforge.net/

- NuSMV
  - http://nusmv.irst.itc.it/



#### Thank You



Have a great day!