## Computer Graphics

## Chapter 7

2D Geometric Transformations

## Chapter 7 <br> Two-Dimensional Geometric Transformations

## Part III.

- OpenGL Functions for Two-Dimensional Geometric Transformations
- OpenGL Geometric Transformation Programming Examples


## OpenGL Geometric Transformation Functions

- Be careful of manipulating the matrix in OpenGL
- OpenGL uses 4X4 matrix for transformation.
- The 16 elements are stored as 1D in column-major order

$$
\left(\begin{array}{cccc}
a_{0} & a_{4} & a_{8} & a_{12} \\
a_{1} & a_{5} & a_{9} & a_{13} \\
a_{2} & a_{6} & a_{9} & a_{14} \\
a_{3} & a_{7} & a_{11} & a_{15}
\end{array}\right) \text { OpenGL transform matrix }
$$

- C and $\mathrm{C}++$ store matrices in row-major order
- If you declare a matrix to be used in OpenGL as

GLfloat M[4][4]; to access the element in row i and column j , you need to refer to it by $\mathrm{M}[\mathrm{j}][\mathrm{i}]$; or, as
GLfloat M[16]; and then you need to convert it to conventional rowmajor order.

## OpenGL Transformations



- Three types
- Modeling, Viewing and Projection

Transformation Use

Viewing
Modeling
Modelview
Projection
Viewport

Specifies the location of the viewer or camera
Moves objects around scene
Describes the duality of viewing and modeling transformations
Clips and sizes the viewing volume
Scales final output to the window

## Standard 2D Viewing Pipeline



## Modeling Transformations



- Modeling transformations: to manipulate / create your model and the particular objects within it.
- Move objects into place, rotates them, and scales them, etc.
- The final appearance of your scene or object can depend greatly on the order in which the modeling transformations are applied.


## Viewing Transformation



- Viewing transformation: to place \& point a camera to view the scene.
- By default, the point of observation is at the origin $(0,0,0)$ looking down the negative z -axis ("into" the monitor screen).
- Objects drawn with positive z values would be behind the observer.
- You can put the point of observation anywhere you want, and looking in any direction. Transformation demo - Nate


## Projection and Viewport Transformations



- Projection transformation: applied to your final Modelview orientation in which way to project.
- Defines how a constructed scene (after all the modeling is done) is translated to the final 2D image on the viewing plane.
- Defines the viewing volume and establishes clipping planes.
- Two types
- Orthographic
- Perspective
- Viewport transformation: maps the 2D projection result of your scene to a window somewhere on your screen.


## OpenGL Transformations

- In OpenGL, all the transformations are described as a multiplication of matrices.
- The mathematics behind these transformations are greatly simplified by the mathematical notation of the matrix.
- Each of the transformations can be achieved by multiplying a matrix that contains the vertices, by a matrix that describes the transformation.


## OpenGL Geometric Transformation Functions

- OpenGL matrix operation function void glMatrixMode(Glenum mode);
- Specify which matrix is the current matrix
- mode: GL_MODELVIEW, GL_PROJECTION, GL_TEXTURE;

GL_COLOR (if ARB_imaging extension is supported).
e.g.: glMatrixMode (GL_MODELVIEW);

- OpenGL matrix operations glLoadIdentity (); / assign identity matrix to the current matrix
/ / ... to apply any transformation matrix to transform your scene ...


## Model-View Matrix: GL_MODELVIEW

- GL_MODELVIEW


4 columns of GL_MODELVIEW matrix

- Store and combine the geometric transformations to models and viewing-coordinate system
- Combine viewing matrix and modeling matrix into one matrix
- Viewing transformation
- For example: gluLookAt()
- Modeling transformation: OpenGL transformation functions
- Translation transformation: m12, m13, m14
- Other Euclidean/affine transformations, such as rotation or scaling: (m0, m1, m2), (m4, m5, m6) and (m8, m9, m10)


## Model-View Matrix: GL_MODELVIEW

- GL_MODELVIEW


4 columns of GL_MODELVIEW matrix

$$
\mathrm{M}=\left[\begin{array}{cccc}
1.0 & 0.0 & 0.0 & 0.0 \\
0.0 & 1.0 & 0.0 & 0.0 \\
0.0 & 0.0 & 1.0 & 0.0 \\
0.0 & 0.0 & 0.0 & 1.0
\end{array}\right]
$$

glMatrixMode (GL_MODELVIEW);
glLoadIdentity (); / / assign identity matrix to the current matrix
These 3 sets

- ( $m 0, m 1, m 2$ ) : +X axis, left vector, $(1,0,0)$ by default
- $(m 4, m 5, m 6):+Y$ axis, up vector, $(0,1,0)$ by default
- $(m 8, m 9, m 10)$ : +Z axis, forward vector, $(0,0,1)$ by default are actually representing 3 orthogonal axes.
glLoadMatrix* (elements16); / / replace the current matrix by your own


## Model-View Matrix: GL_MODELVIEW

## Example

glMatrixMode (GL_MODELVIEW); glLoadIdentity ();
GLfloat elems [16];
GLint k;
for $(\mathrm{k}=0 ; \mathrm{k}<16 ; \mathrm{k}++$ )
elems $[\mathrm{k}]=$ float $(\mathrm{k})$;
glLoadMatrixf (elems);


4 columns of GL_MODELVIEW matrix

$$
\mathrm{M}=\left[\begin{array}{cccc}
0.0 & 4.0 & 8.0 & 12.0 \\
1.0 & 5.0 & 9.0 & 13.0 \\
2.0 & 6.0 & 10.0 & 14.0 \\
3.0 & 7.0 & 11.0 & 15.0
\end{array}\right]
$$

glMatrixMode()
http: / /www.opengl.org/sdk/docs/man/

## OpenGL Geometric Transformation Functions

- Basic OpenGL geometric transformations on the matrix:
glTranslate* (tx, ty, tz);
[ glTranslatef $(25.0,-10.0,0.0)$; ] for 2 D , set $\mathrm{tz}=0$.
- Post-multiplies the current matrix by a matrix that moves the object by the given $\mathrm{x}-\mathrm{y}$, $\mathrm{y}^{-}$, and $z$-values
glScale* (sx, sy, sz);
[ glScalef (2.0, -3.0, 1.0); ]
- Post-multiplies the current matrix by a matrix that scales an object about the origin.

None of sx, sy or sz is zero.
glRotate* (theta, vx, vy, vz);
[ glRotatef (90.0, 0.0, 0.0, 1.0); ]

- Post-multiplies the current matrix by a matrix that rotates the object in a counterclockwise direction. vector $\mathrm{v}=(\mathrm{vx}, \mathrm{vy}, \mathrm{vz})$ defines the orientation for the rotation axis that passes though the coordinate origin. ( the rotation center is $(0,0,0)$ )


## OpenGL: Order in Matrix Multiplication

```
glMatrixMode (GL_MODELVIEW);
glLoadIdentity (); / / Set current matrix to the identity.
glMultMatrixf (elemsM2); / / Post-multiply identity by matrix M2.
glMultMatrixf (elemsM1); / / Post-multiply M2 by matrix M1.
glBegin (GL_POINTS)
    glVertex3f (vertex);
glEnd( );
Modelview matrix successively contains:
I(identity), M2, M2. M1
```

The concatenated matrix is:

$$
\mathrm{M}=\mathrm{M} 2 \cdot \mathrm{M} 1
$$

The transformed vertex is:
M2•(M1 - vertex)

In OpenGL, a transformation sequence is applied in reverse order of which it is specified.

## OpenGL: Order in Matrix Multiplication

- Example

> / / rotate object 30 degrees around Z-axis glRotatef $(30.0,0.0,0.0,1.0) ;$
> / / move object to $(2.0,3.0,0.0)$ glTranslatef $(2.0,3.0,0.0) ;$ drawObject ()

The object will be translated first then rotated.

## OpenGL Geometric Trans. Programming Examples

glMatrixMode (GL_MODELVIEW); / / Identity matrix

```
glColor3f (0.0, 0.0, 1.0); / / Set current color to blue
glRecti (50, 100, 200, 150); / / Display blue rectangle.
glColor3f (1.0, 0.0, 0.0); / / Red
glTranslatef (-200.0,-50.0, 0.0); / / Set translation parameters.
glRecti (50, 100, 200, 150); / / Display red, translated rectangle.
glLoadIdentity (); / / Reset current matrix to identity.
glRotatef (90.0, 0.0, 0.0, 1.0); / / Set 90-deg, rotation about z axis.
glRecti (50, 100, 200, 150); / / Display red, rotated rectangle.
glLoadIdentity (); / / Reset current matrix to identity.
glScalef (-0.5, 1.0, 1.0); / / Set scale-reflection parameters.
glRecti (50, 100, 200, 150); // Display red, transformed rectangle.
```



## Summary

- Basic 2D geometric transformations
- Translation
- Rotation
- Scaling
- Reflection, shearing...
- Combination of these transformations
- Homogeneous coordinate representation
- OpenGL geometric transformation functions
- GL_MODELVIEW matrix
- Order in multiple matrix multiplication
- Example

