

# Chapter 7 Two-Dimensional Geometric Transformations

### Part III.

- OpenGL Functions for Two-Dimensional Geometric Transformations
- OpenGL Geometric Transformation Programming Examples

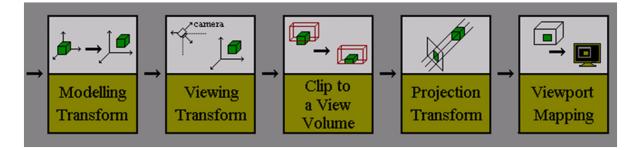
### **OpenGL Geometric Transformation Functions**

- <u>Be careful of manipulating the matrix in OpenGL</u>
  - OpenGL uses 4X4 matrix for transformation.
  - The 16 elements are stored as 1D in *column-major order*

$$\begin{pmatrix} a_{0} & a_{4} & a_{8} & a_{12} \\ a_{1} & a_{5} & a_{9} & a_{13} \\ a_{2} & a_{6} & a_{10} & a_{14} \\ a_{3} & a_{7} & a_{11} & a_{15} \end{pmatrix}$$
OpenGL transform matrix

- C and C++ store matrices in *row-major order*
- If you declare a matrix to be used in OpenGL as GLfloat M[4][4]; to access the element in row i and column j, you need to refer to it by M[j][i]; or, as GLfloat M[16]; and then you need to convert it to conventional *row-major order*.

# **OpenGL Transformations**

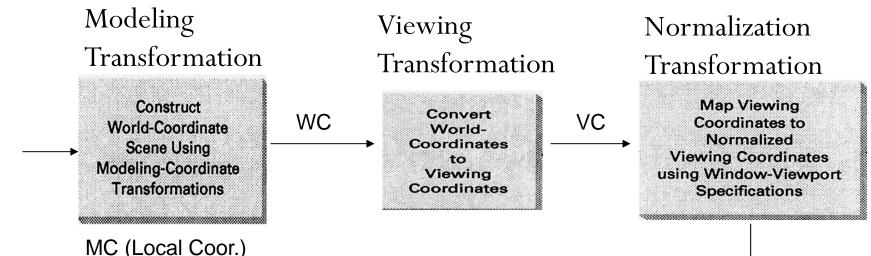


- Three types
  - Modeling, Viewing and Projection

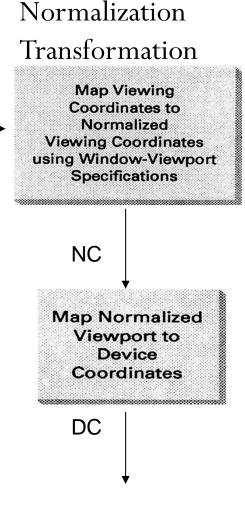
| Transformation | Use |
|----------------|-----|
|----------------|-----|

| Viewing    | Specifies the location of the viewer or camera                |
|------------|---|
| Modeling   | Moves objects around scene                                    |
| Modelview  | Describes the duality of viewing and modeling transformations |
| Projection | Clips and sizes the viewing volume                            |
| Viewport   | Scales final output to the window                             |

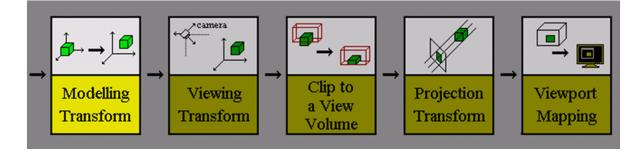
# Standard 2D Viewing Pipeline



- To make the viewing process independent of any output device, viewing coordinates is converted to normalized coordinates.
- Clipping is usually performed in normalized coordinates.

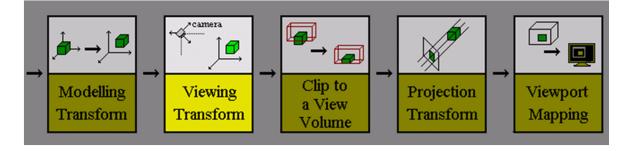


# **Modeling Transformations**



- *Modeling transformations:* to manipulate/create your model and the particular objects within it.
  - Move objects into place, rotates them, and scales them, etc.
  - The final appearance of your scene or object can depend greatly on the order in which the modeling transformations are applied.

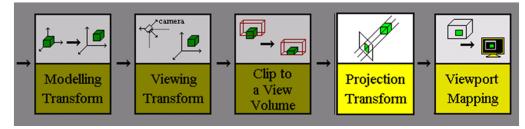
## **Viewing Transformation**



- *Viewing transformation:* to place & point a camera to view the scene.
  - By default, the point of observation is at the origin (0,0,0) looking down the negative z-axis ("into" the monitor screen).
    - Objects drawn with positive z values would be behind the observer.
  - You can put the point of observation anywhere you want, and looking in any direction.

Transformation demo - Nate

# **Projection and Viewport Transformations**



- *Projection transformation:* applied to your final Modelview orientation in which way to project.
  - Defines how a constructed scene (after all the modeling is done) is translated to the final 2D image on the viewing plane.
  - Defines the viewing volume and establishes clipping planes.
  - Two types
    - Orthographic
    - Perspective
- *Viewport transformation:* maps the 2D projection result of your scene to a window somewhere on your screen.

# **OpenGL Transformations**

- In OpenGL, all the transformations are described as a **multiplication of matrices**.
  - The mathematics behind these transformations are greatly simplified by the mathematical notation of the matrix.
  - Each of the transformations can be achieved by multiplying a **matrix** that contains the vertices, by a **matrix** that describes the transformation.

### **OpenGL Geometric Transformation Functions**

- OpenGL matrix operation function void glMatrixMode(Glenum mode);
  - Specify which matrix is the current matrix
  - *mode:* GL\_MODELVIEW, GL\_PROJECTION, GL\_TEXTURE;

GL\_COLOR (if ARB\_imaging extension is supported).

e.g.: glMatrixMode (GL\_MODELVIEW);

• OpenGL matrix operations

glMatrixMode (GL\_MODELVIEW); Set up the matrix for geometric transformations

glLoadIdentity (); // assign identity matrix to the current matrix

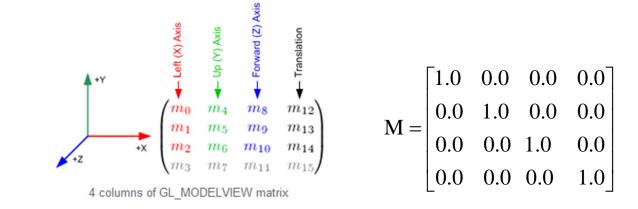
//... to apply any transformation matrix to transform your scene  $\dots$ 

#### Model-View Matrix: GL\_MODELVIEW GL\_MODELVIEW Left (X) Axis 🔶 Up (Y) Axis Translation Î Clip to Modelling Viewing Projection Viewport a View Transform Transform Transform Mapping $m_4 - m_8$ $m_{12}$ Volume $m_5$ $m_9$ $m_{13}$ $m_1$ +X $m_{10}$ $m_{14}$

- Store and combine the geometric transformations to models and viewing-coordinate system
  - Combine viewing matrix and modeling matrix into one matrix
- Viewing transformation
  - For example: **gluLookAt()**
- Modeling transformation: OpenGL transformation functions
  - Translation transformation: *m12*, *m13*, *m14*
  - Other Euclidean/affine transformations, such as rotation or scaling: (m0, m1, m2), (m4, m5, m6) and (m8, m9, m10)

<sup>4</sup> columns of GL\_MODELVIEW matrix

# Model-View Matrix: GL\_MODELVIEW GL\_MODELVIEW



#### glMatrixMode (GL\_MODELVIEW);

glLoadIdentity (); // assign identity matrix to the current matrix

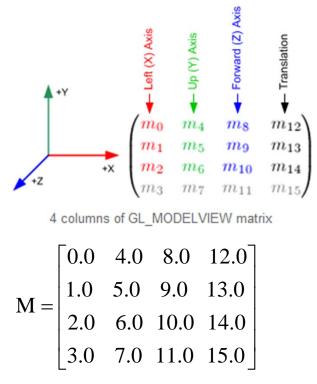
These 3 sets

- (m0, m1, m2) : +X axis, *left* vector, (1, 0, 0) by default
- (m4, m5, m6) : +Y axis, up vector, (0, 1, 0) by default
- (*m8*, *m9*, *m10*) : +Z axis, *forward* vector, (0, 0, 1) by default are actually representing 3 orthogonal axes.

glLoadMatrix\* (elements16); // replace the current matrix by your own

# Model-View Matrix: GL\_MODELVIEW

### 



### glMatrixMode()

http://www.opengl.org/sdk/docs/man/

### **OpenGL Geometric Transformation Functions**

 Basic OpenGL geometric transformations on the matrix: glTranslate\* (tx, ty, tz);

[ glTranslatef (25.0, -10.0, 0.0); ] for 2D, set tz = 0.

- Post-multiplies the current matrix by a matrix that moves the object by the given x-, y-, and z-values

glScale\* (sx, sy, sz);

[glScalef (2.0, -3.0, 1.0);]

Post-multiplies the current matrix by a matrix that scales an object about the origin.
 None of sx, sy or sz is zero.

**glRotate\*** (theta, vx, vy, vz); [ glRotatef (90.0, 0.0, 0.0, 1.0); ]

Post-multiplies the current matrix by a matrix that rotates the object in a counterclockwise direction. vector v=(vx, vy, vz) defines the orientation for the rotation axis that passes though the coordinate origin. ( the rotation center is (0, 0, 0) )

# **OpenGL: Order in Matrix Multiplication**

```
glMatrixMode (GL_MODELVIEW);
glLoadIdentity (); //Set current matrix to the identity.
glMultMatrixf (elemsM2); //Post-multiply identity by matrix M2.
glMultMatrixf (elemsM1); //Post-multiply M2 by matrix M1.
```

**glBegin** (GL\_POINTS) glVertex3f (vertex);

glEnd();

Modelview matrix successively contains: I(identity), M2, M2 M1 The concatenated matrix is: M=M2·M1 The transformed vertex is: M2·(M1 · vertex)

In OpenGL, a transformation sequence is applied in reverse order of which it is specified.

**OpenGL: Order in Matrix Multiplication** 

• Example

// rotate object 30 degrees around Z-axis
glRotatef(30.0, 0.0, 0.0, 1.0);
// move object to (2.0, 3.0, 0.0)
glTranslatef(2.0, 3.0, 0.0);
drawObject();

The object will be **translated** first then **rotated**.

### **OpenGL Geometric Trans. Programming Examples**

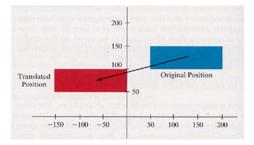
glMatrixMode (GL\_MODELVIEW); //Identity matrix

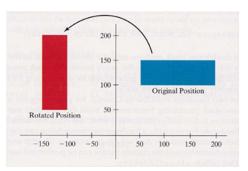
glColor3f (0.0, 0.0, 1.0); // Set current color to blue glRecti (50, 100, 200, 150); // Display blue rectangle.

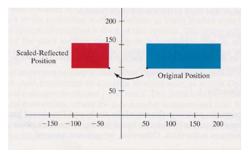
glColor3f (1.0, 0.0, 0.0); // Red glTranslatef (-200.0, -50.0, 0.0); // Set translation parameters. glRecti (50, 100, 200, 150); // Display red, translated rectangle.

glLoadIdentity (); // Reset current matrix to identity. glRotatef (90.0, 0.0, 0.0, 1.0); // Set 90-deg, rotation about z axis. glRecti (50, 100, 200, 150); // Display red, rotated rectangle.

glLoadIdentity ();// Reset current matrix to identity.glScalef (-0.5, 1.0, 1.0);// Set scale-reflection parameters.glRecti (50, 100, 200, 150);// Display red, transformed rectangle.







# Summary

- Basic 2D geometric transformations
  - Translation
  - Rotation
  - Scaling
  - Reflection, shearing...
  - Combination of these transformations
- Homogeneous coordinate representation
- OpenGL geometric transformation functions
  - GL\_MODELVIEW matrix
  - Order in multiple matrix multiplication
  - Example